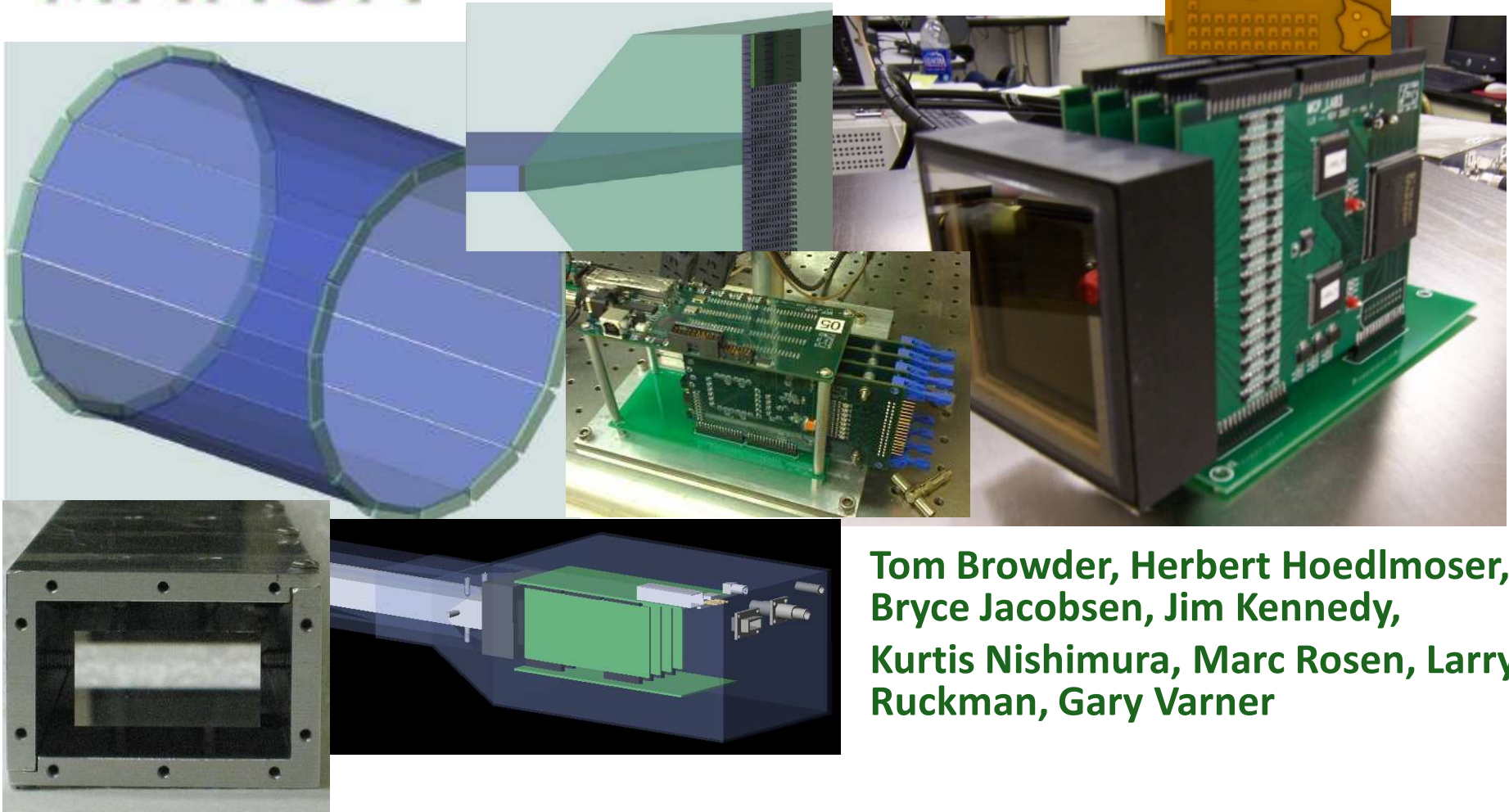


# Imaging TOP (iTOP), Cosmic Ray Test Stand &

UNIVERSITY OF HAWAII AT  
**MANOA**

## PID Readout Update

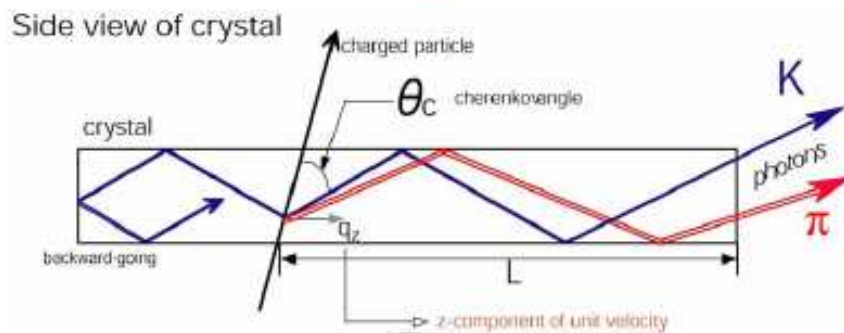


Tom Browder, Herbert Hoedlmoser,  
Bryce Jacobsen, Jim Kennedy,  
Kurtis Nishimura, Marc Rosen, Larry  
Ruckman, Gary Varner

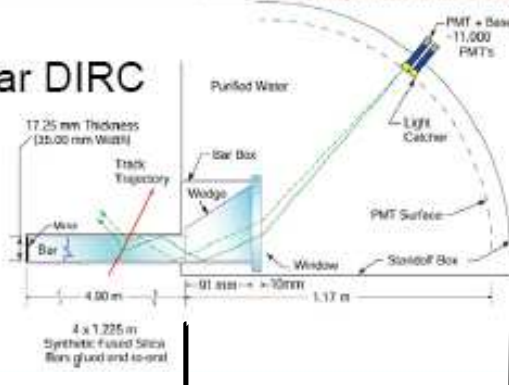
Kurtis Nishimura | SuperKEKB PID Parallel Session | December 11, 2008

# imaging TOP (iTOP)

Concept: Use best of both TOP (timing) and DIRC and fit in Belle PID envelope



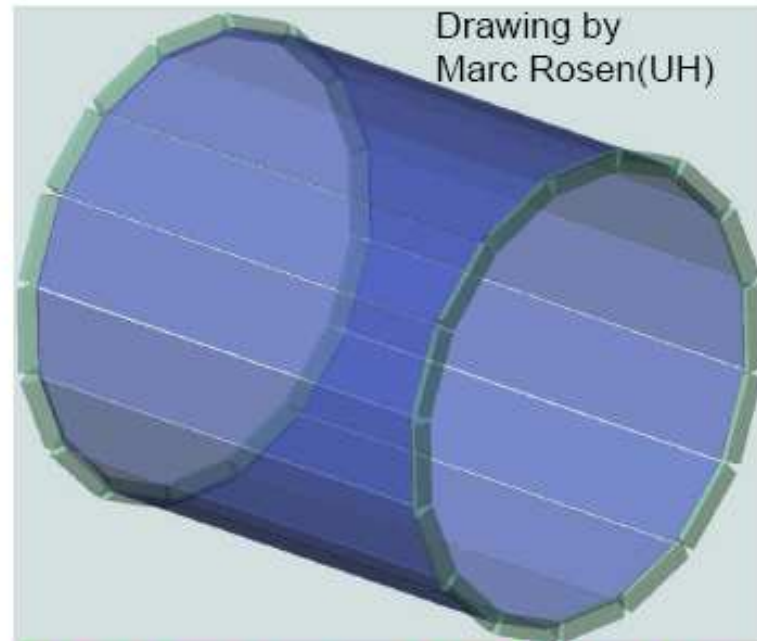
BaBar DIRC



> 1 meter: Need more compact solution.

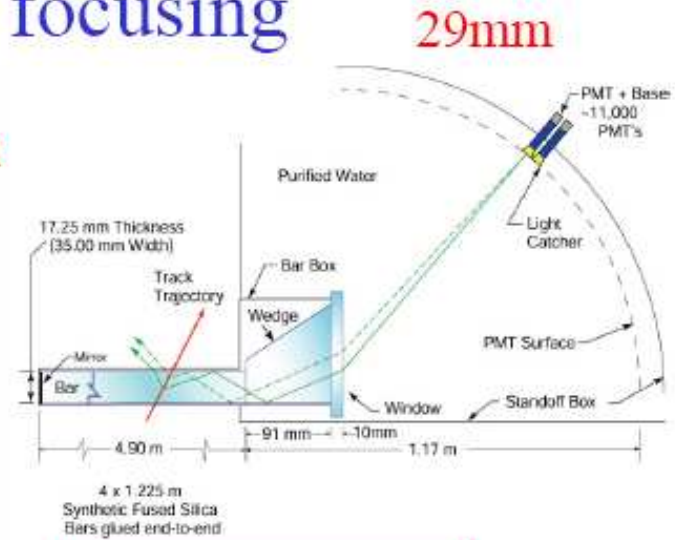
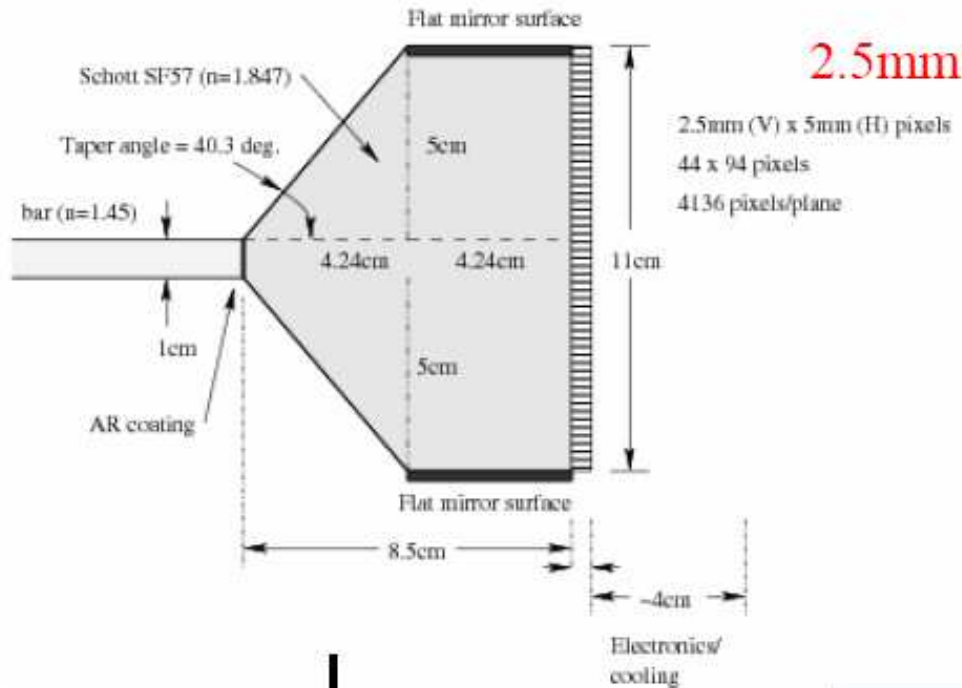
## iTOP Concept Drawing

Drawing by Marc Rosen(UH)

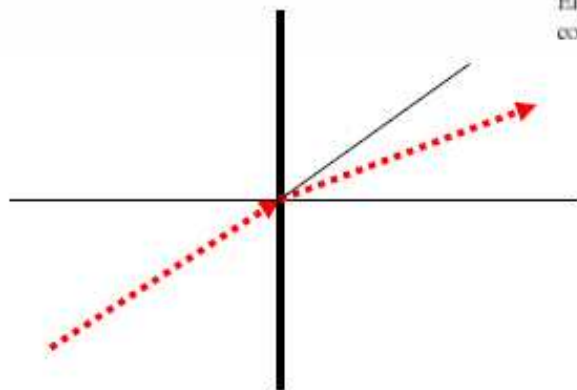
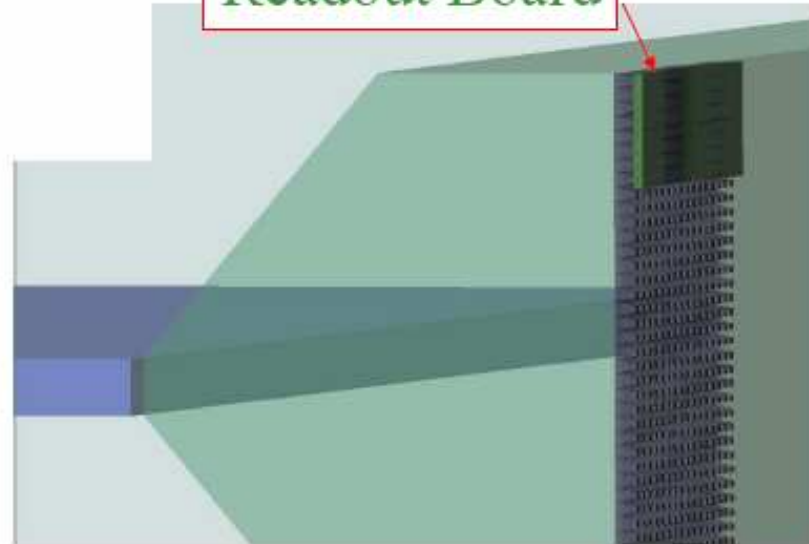


- Use new, compact solid-state photon detectors, new high-density electronics
- Use simultaneous  $T$ ,  $\theta_c$  [measured-predicted] for maximum  $K/\pi$  separation
- Keep pixel size comparable to DIRC

# Simple refractive focusing



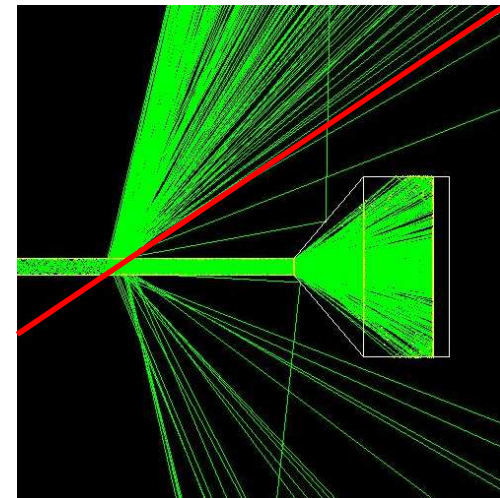
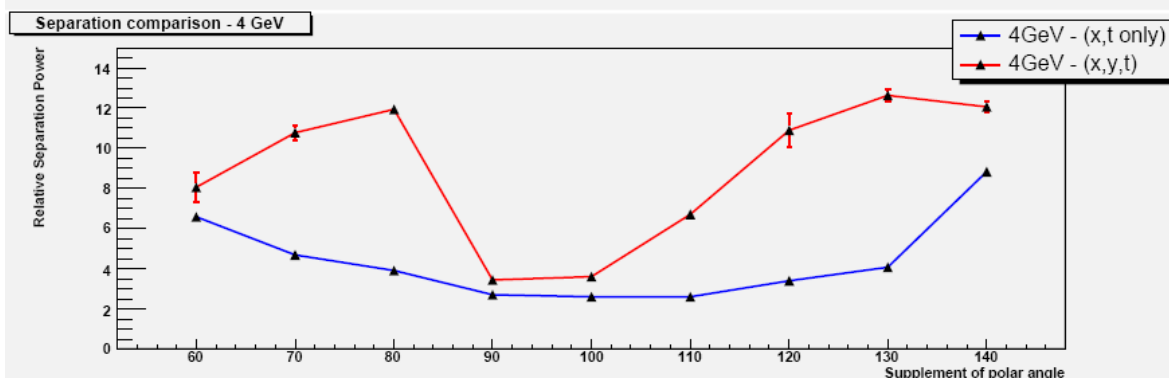
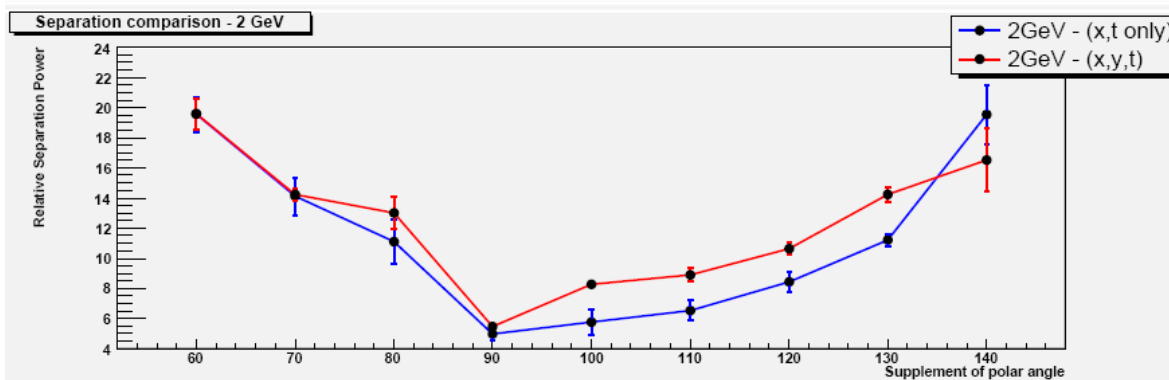
Readout Board



Refraction in stand-off block compacts the image.

# Previous GEANT4 Simulation

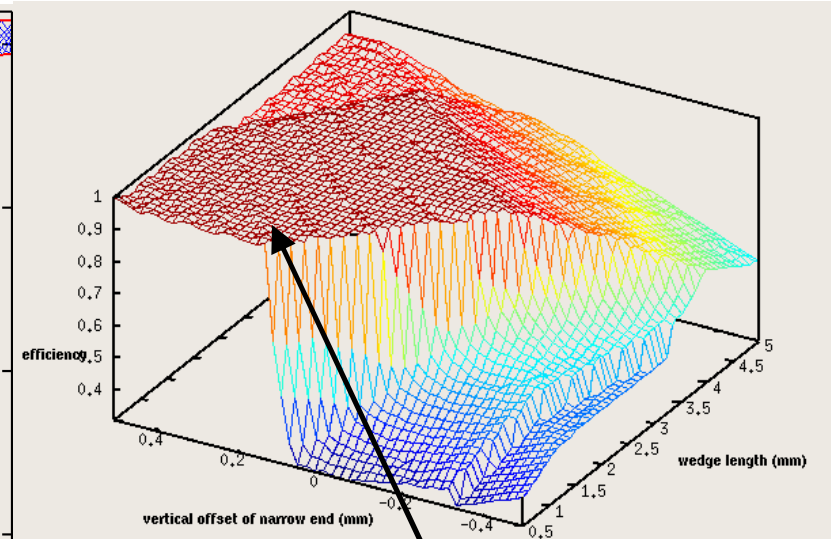
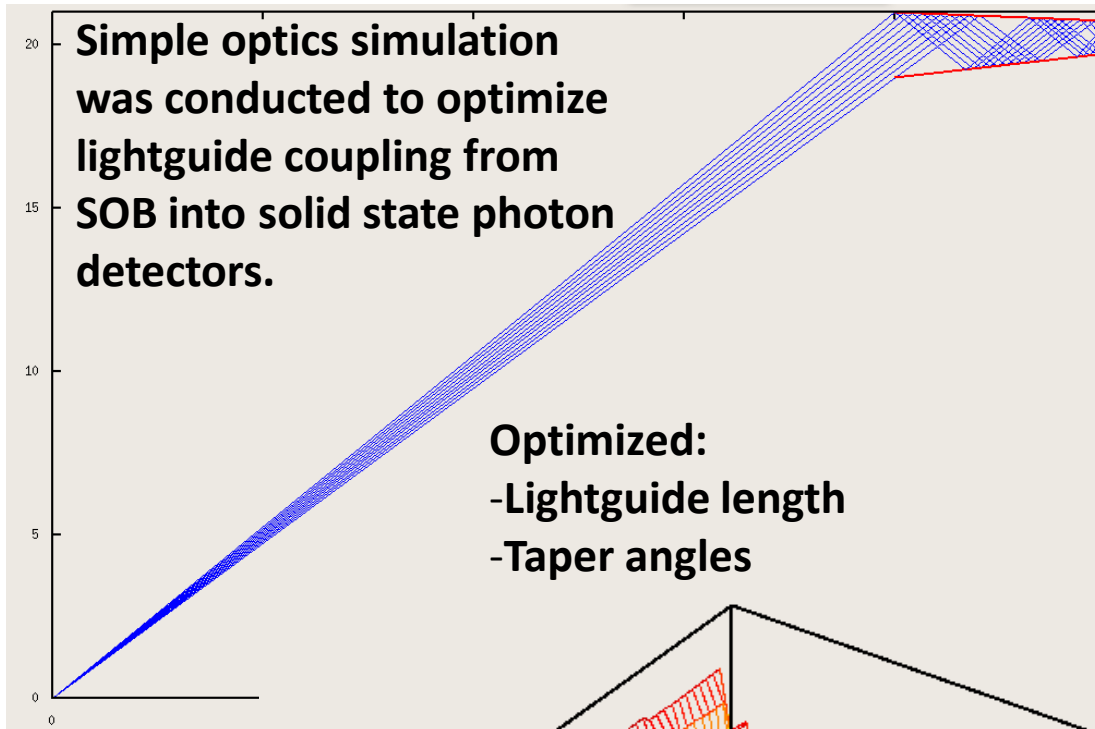
- Simulations of relative  $K/\pi$  separation based on  $\Delta\text{Log}(L)$  method:



Some challenges with initial assumptions have been found. Method needs testing & validation.

➔ Adding second dimension of image reconstruction improves separation power!

# Refractive Focusing Challenges



With small offsets from bar axis, coupling can be done very efficiently (~100%).

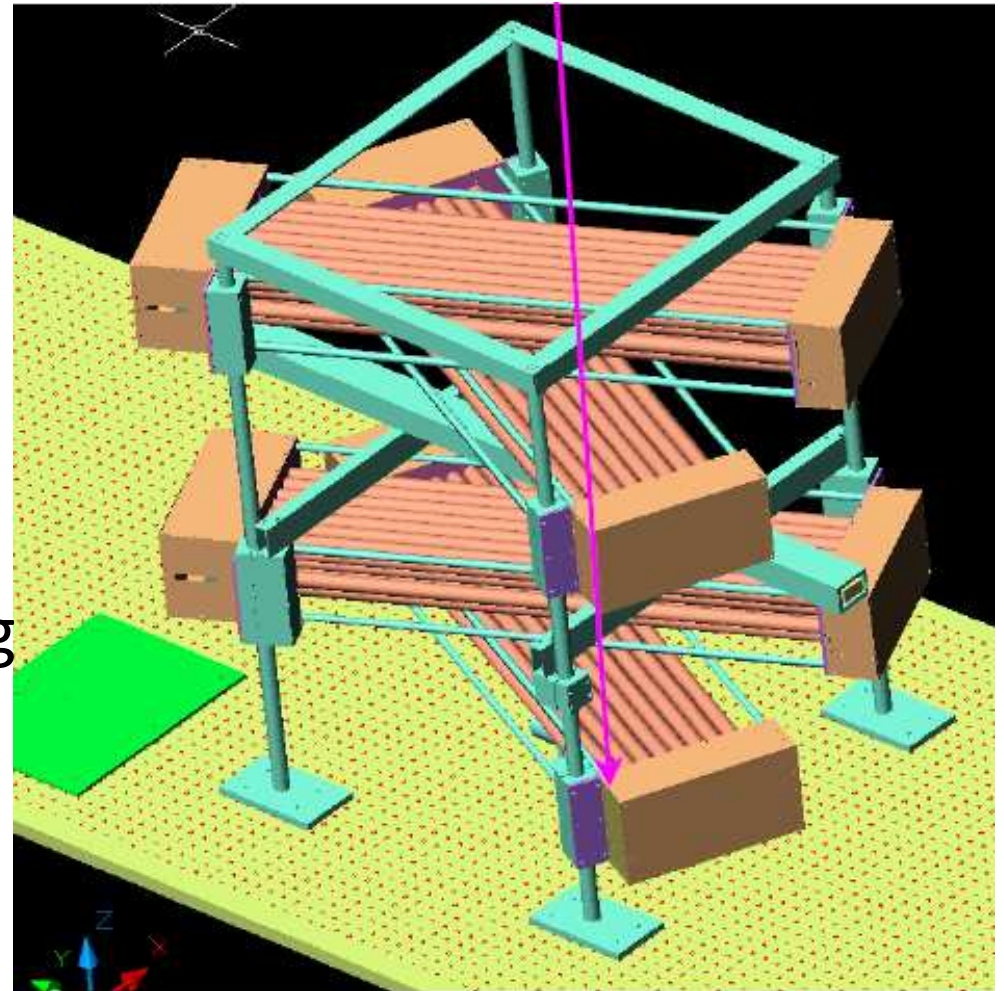
Off axis, maximum efficiency is limited (~40%) → light trapped.

Possible solutions:

- Faceted SOB
- Different detectors

# Hawaii Testbed for Innovative Detectors & Electronics (HI-TIDE)

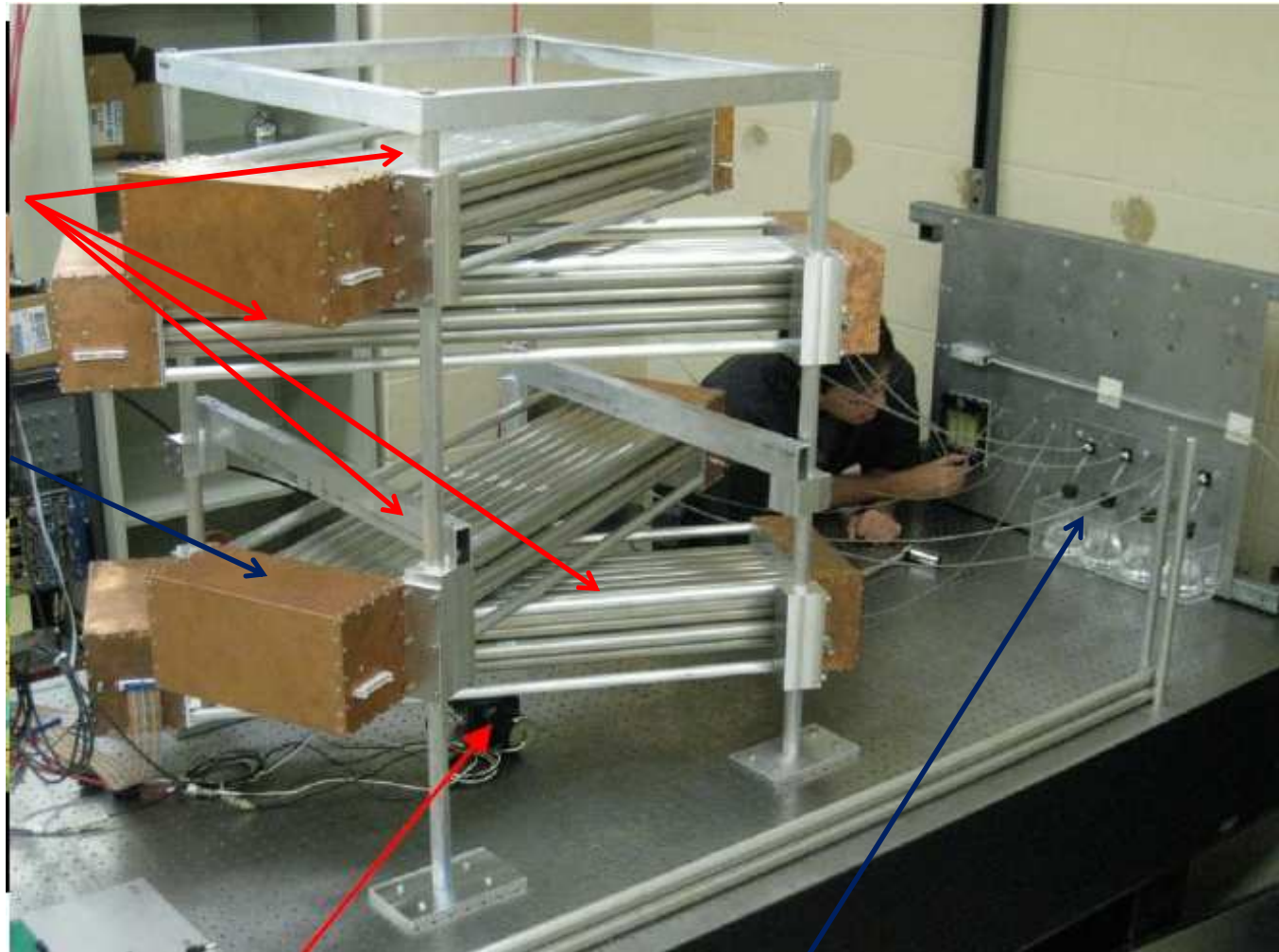
- Cosmic muon test stand for validation of simulations, testing of electronics in Hawaii.
- Initial system:
  - Basic tracking system completed, initial testing performed.
  - Quartz bar
- Upgrades underway.



# Initial HI-TIDE System

**128x Drift  
tubes: Al, 1" OD**

**4x 32x  
Preamplifiers  
(Inside copper  
cases)**

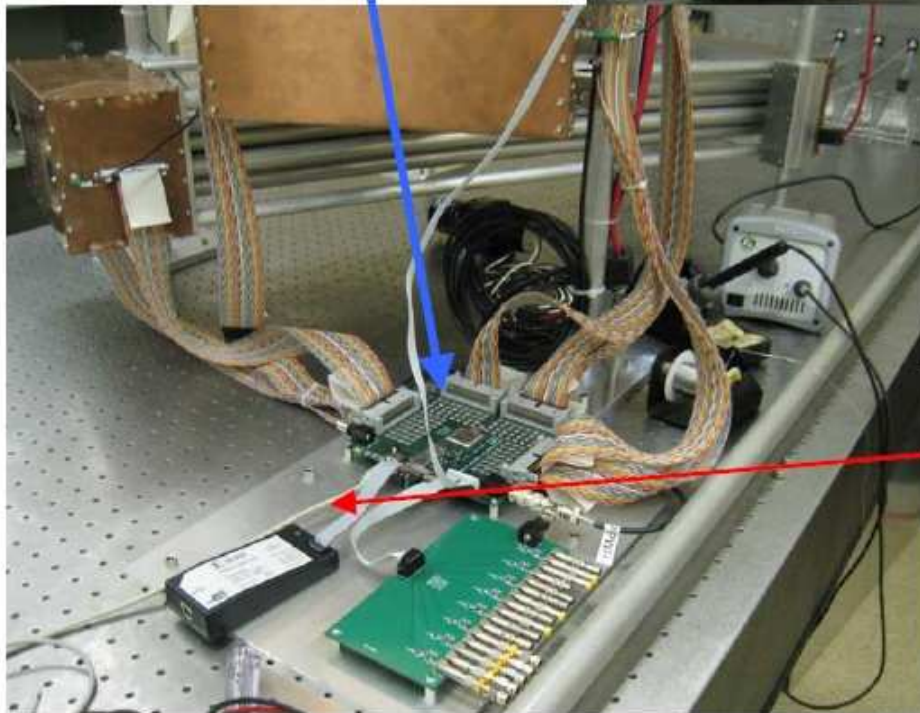
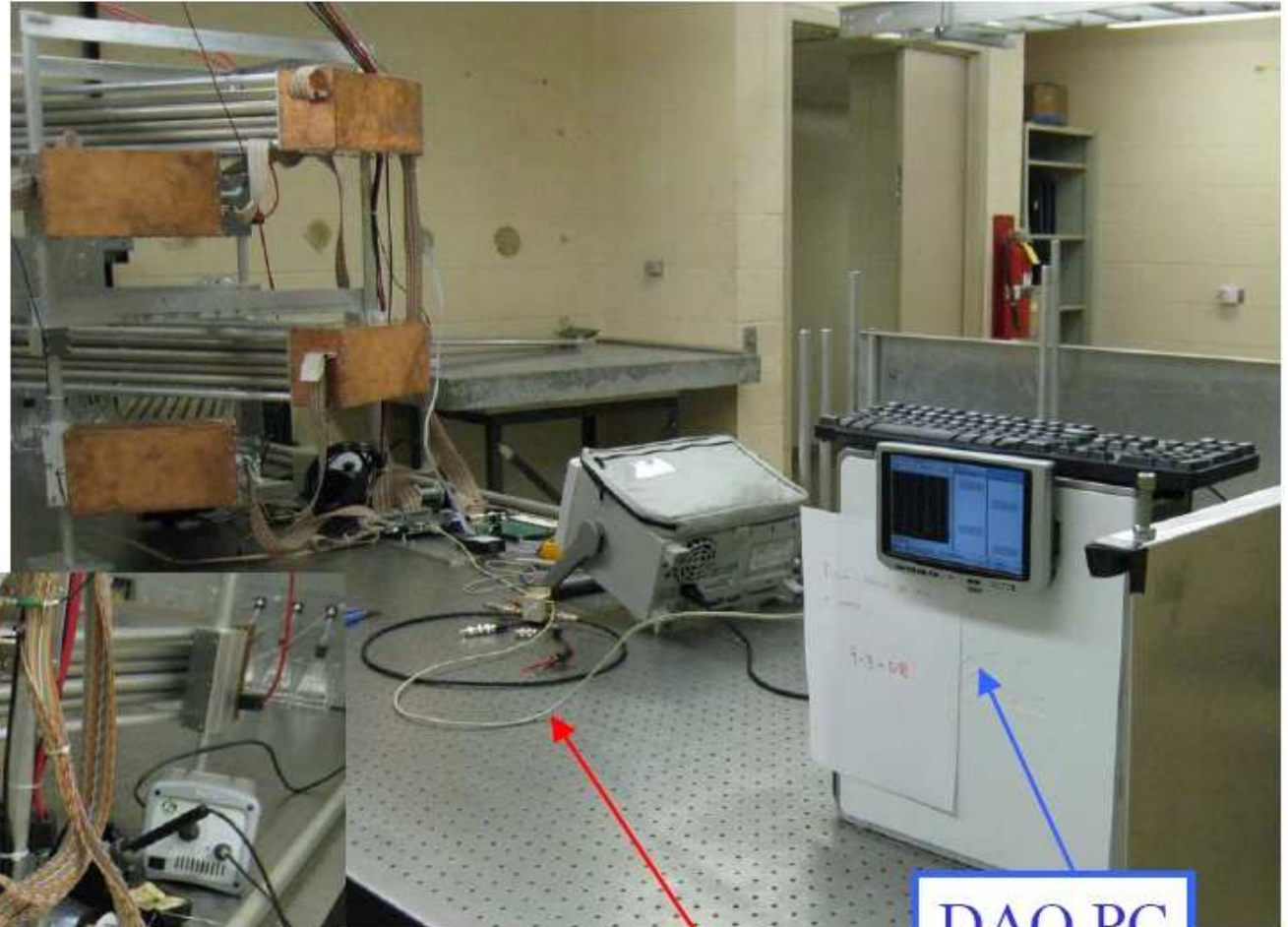


**Precision Timing Block –  
Radiator bar w/ 2 PMTS**

**Gas – 90% Argon, 10% CO<sub>2</sub>**

# Cosmic Test Bench - Electronics

- 128 channel Discriminator and TDC board (TRAMP)



USB2 link  
(drift-tubes)

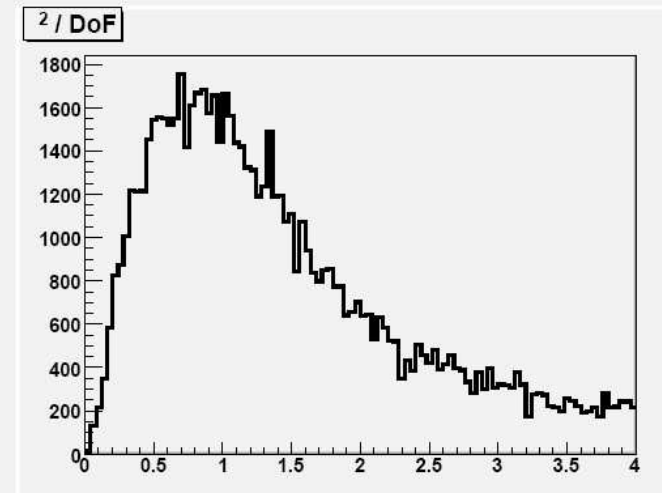
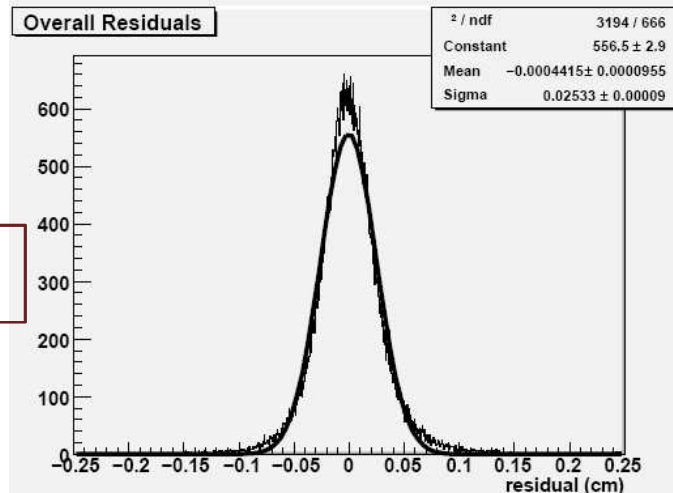
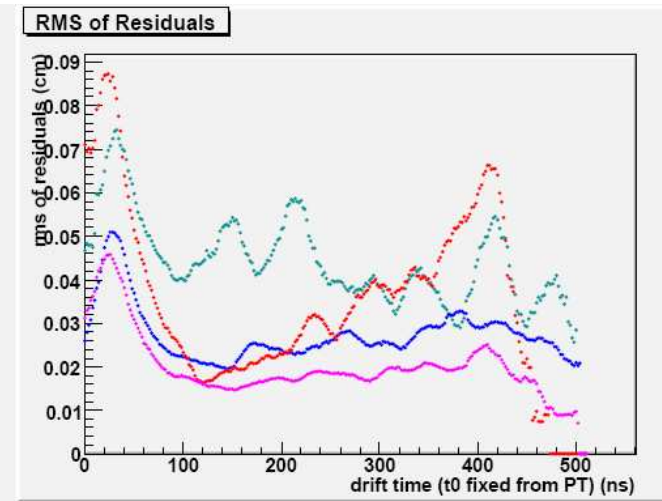
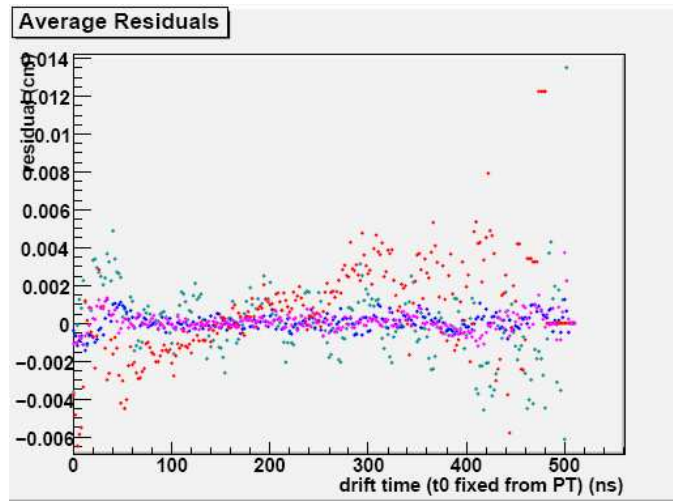
DAQ PC



# Calibration of Drift Tubes



Fits performed in individual planes.  
Residuals used iteratively to calibrate (results shown after 7 iterations).

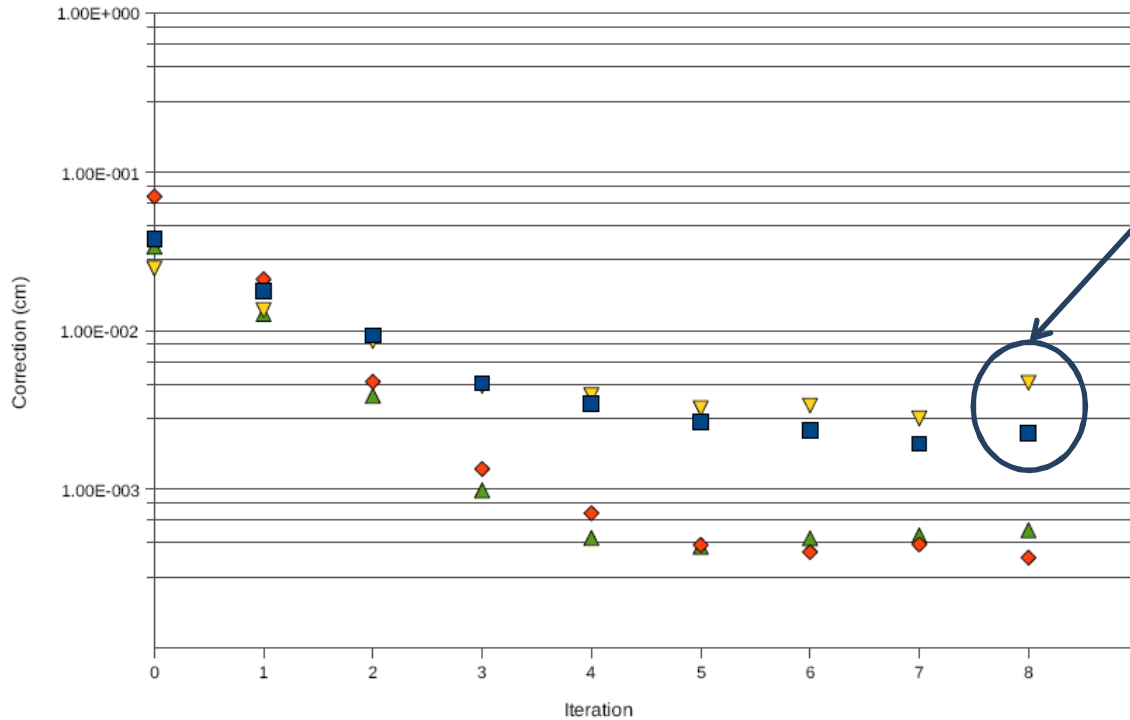


Overall  $\sigma_r = 25 \mu\text{m}$

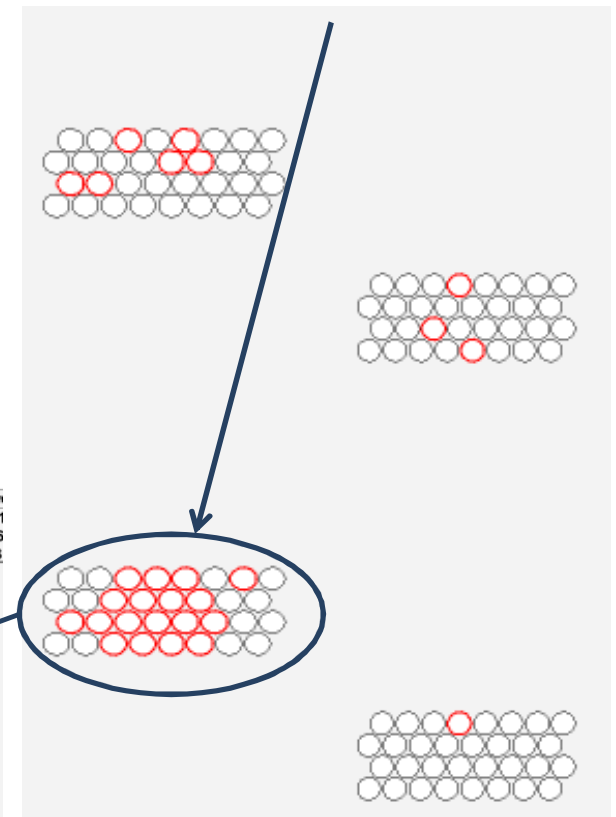
$$\sqrt{\sum_i \frac{\Delta_i^2}{N_{bins}}}$$

# Drift Tube Issues / Upgrades

Root Mean Square Correction vs. Iteration



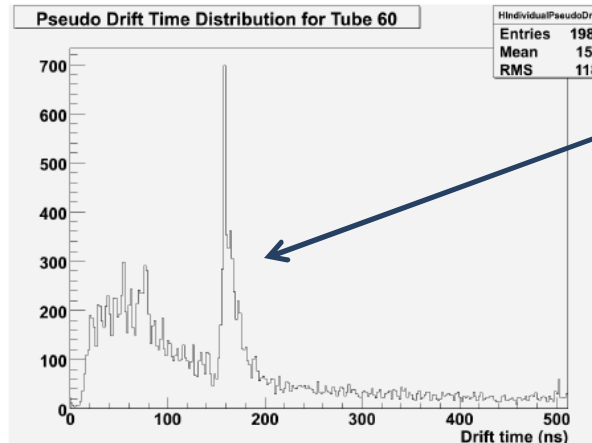
Problem in layers  
1/3?  
Maybe due to  
noise/crosstalk:



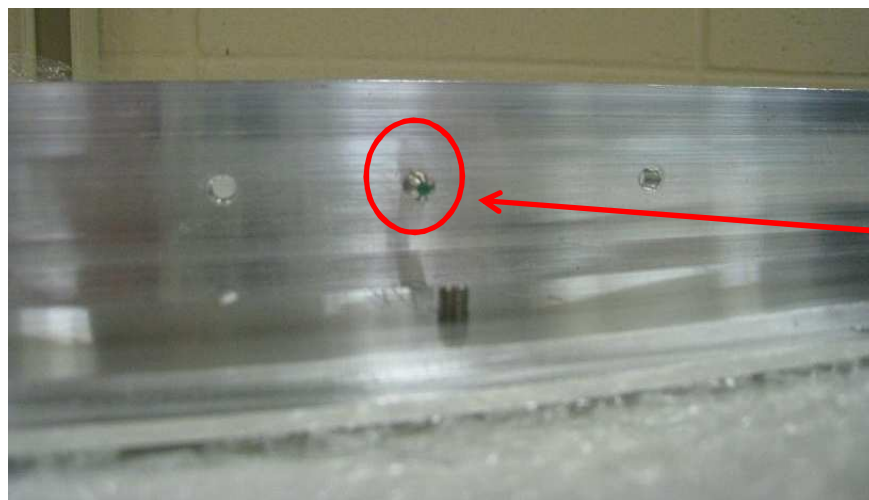
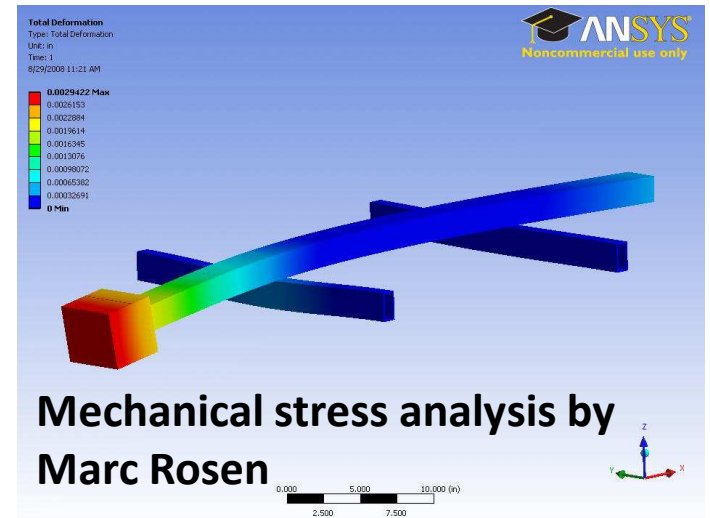
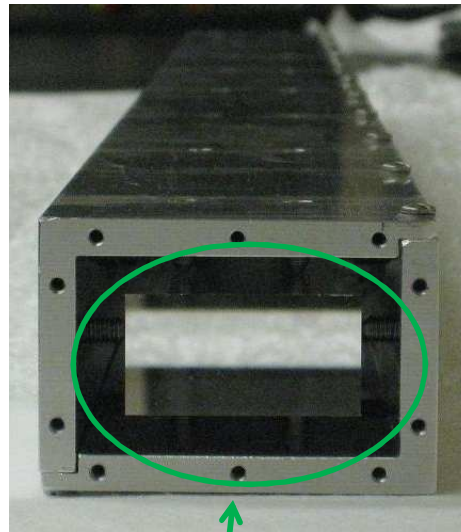
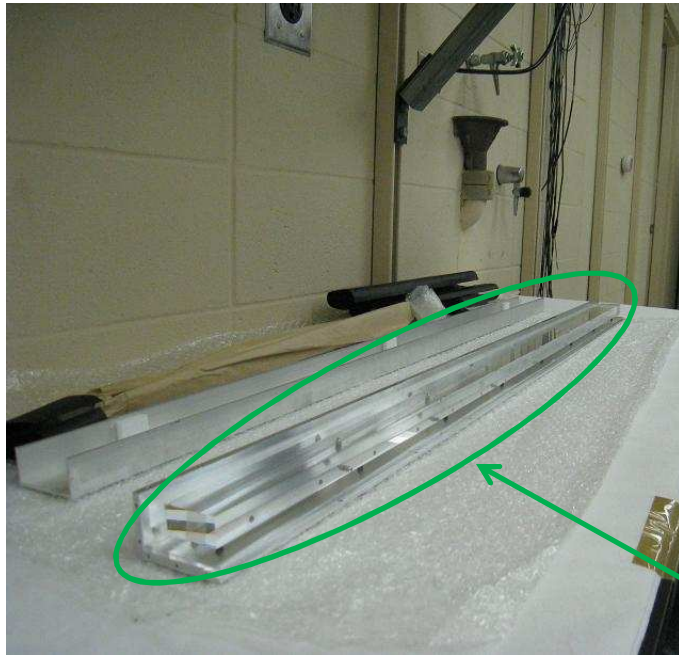
Crosstalk is difficult to detect from TDC values alone.

➔ Upgrades underway:

- Full waveform readout with BLAB2 (fiberoptic).
- Readout from both sides of drift tubes.



# Quartz Bar Assembly & Support



Quartz Bar (Zygo)

• 2 x 4 x 120 cm

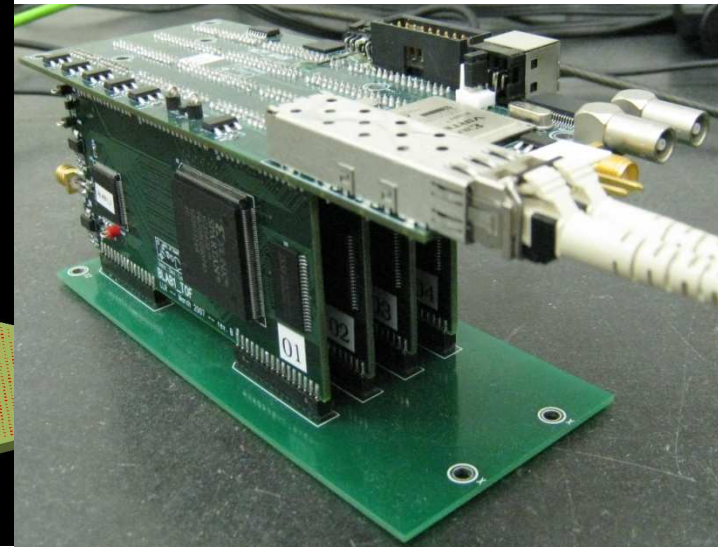
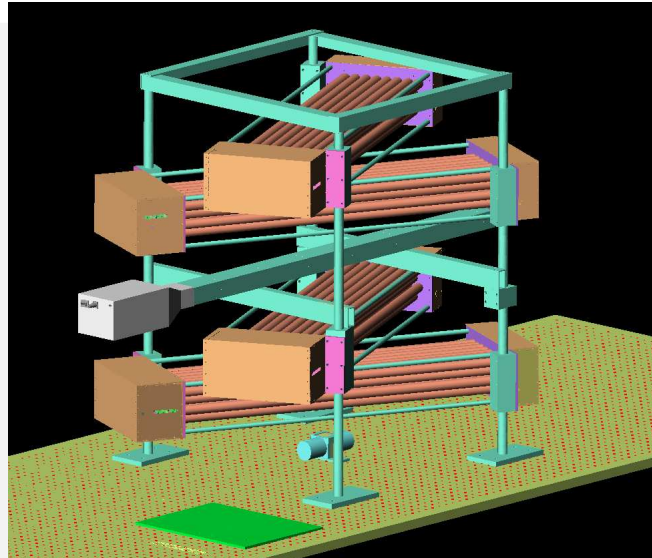
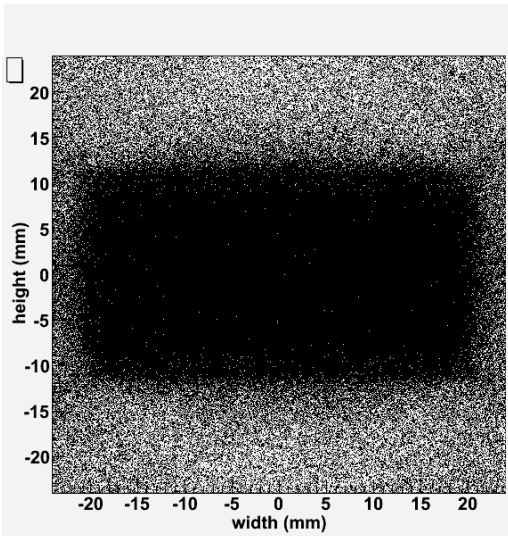
•  $n = 1.47$

Nylon tipped  
screws support  
bar.

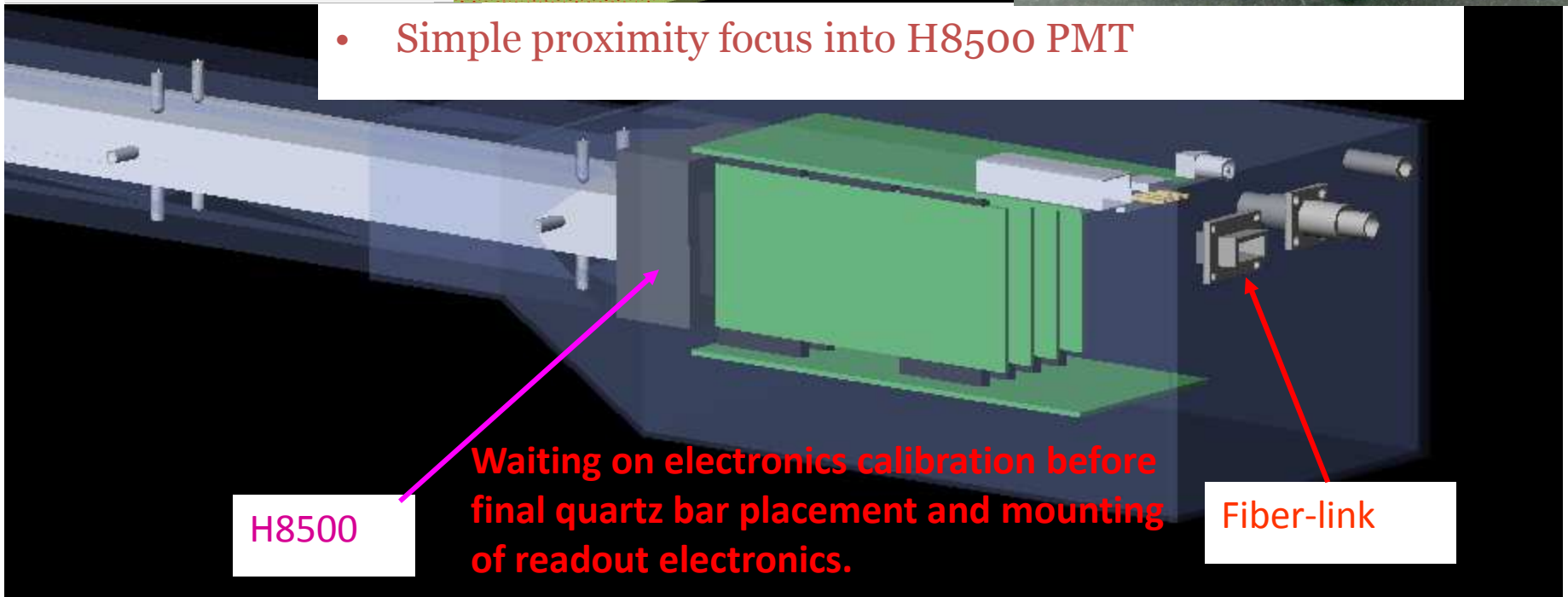
Mechanical  
cantilever support



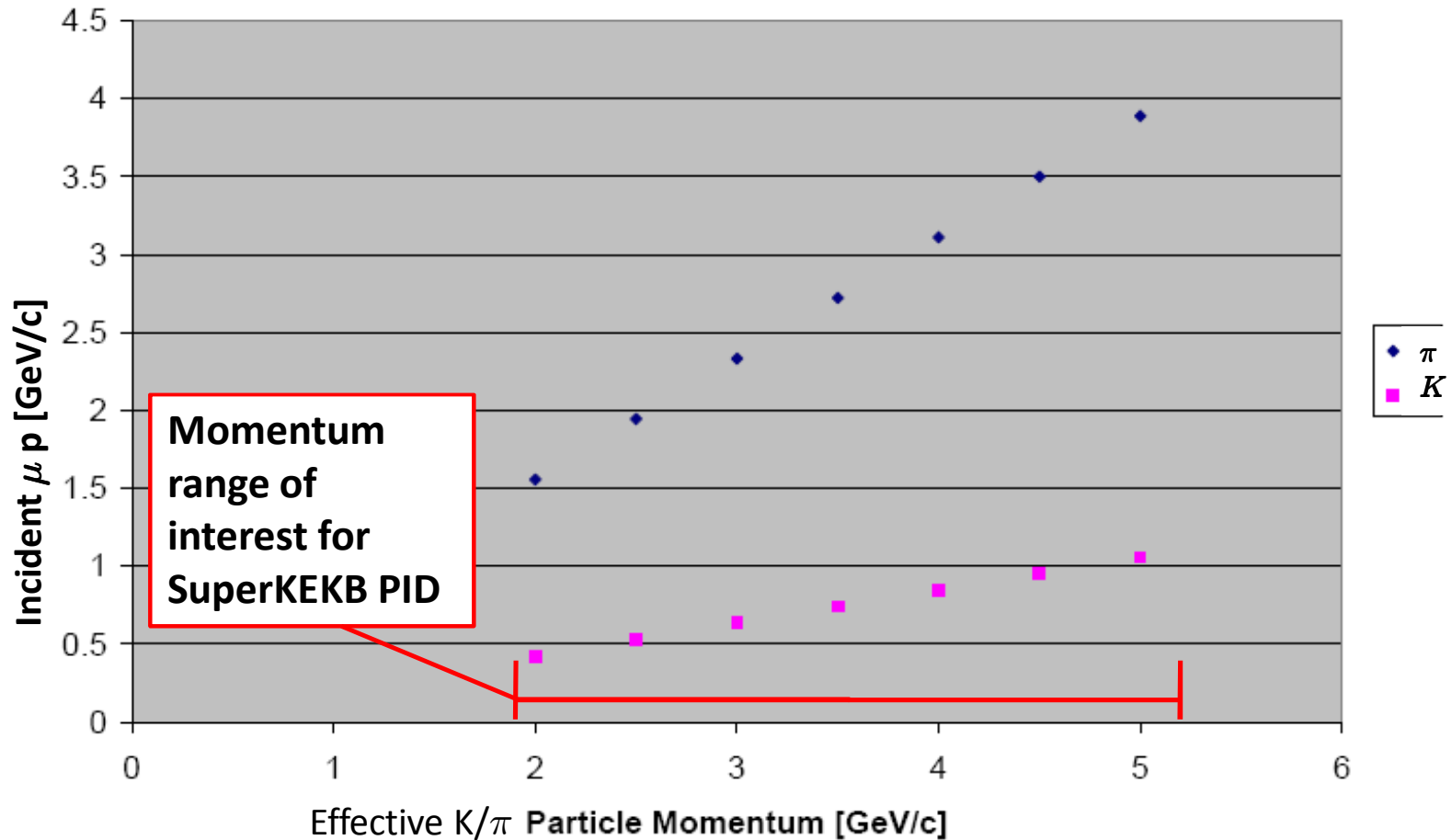
# Initial Quartz bar test



- Simple proximity focus into H8500 PMT

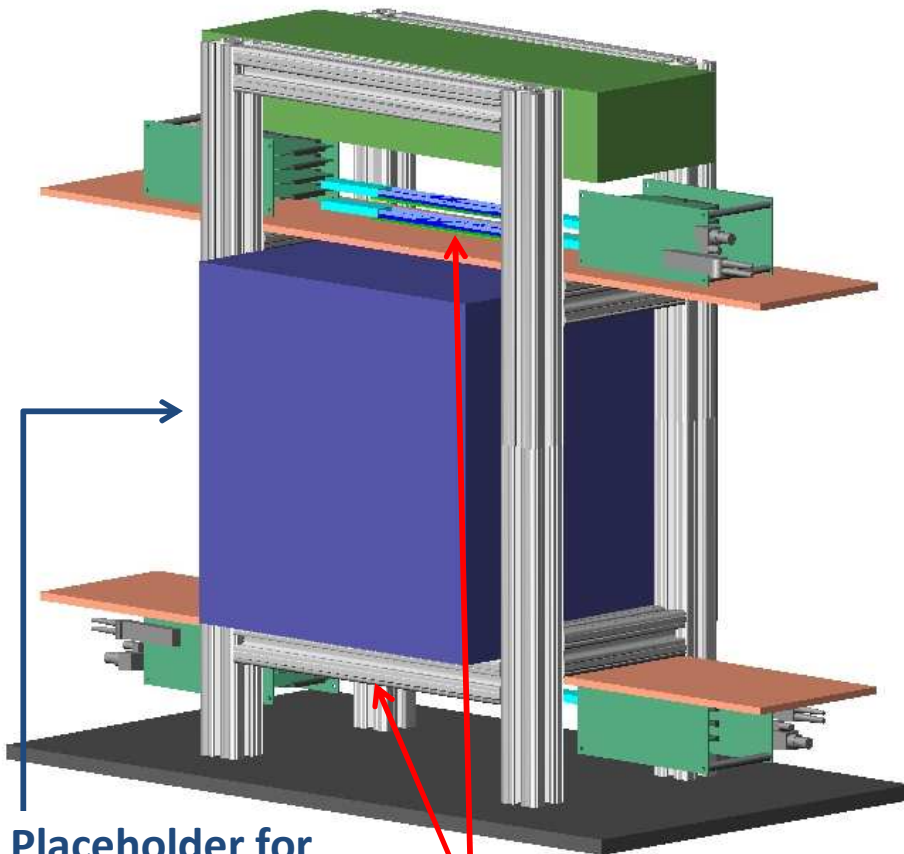


## Muon momentum emulation [GeV/c]



- Need momentum measurement to test K/ $\pi$  performance!
- Magnet assembly will measure momentum → Initial simulation & magnet design have begun

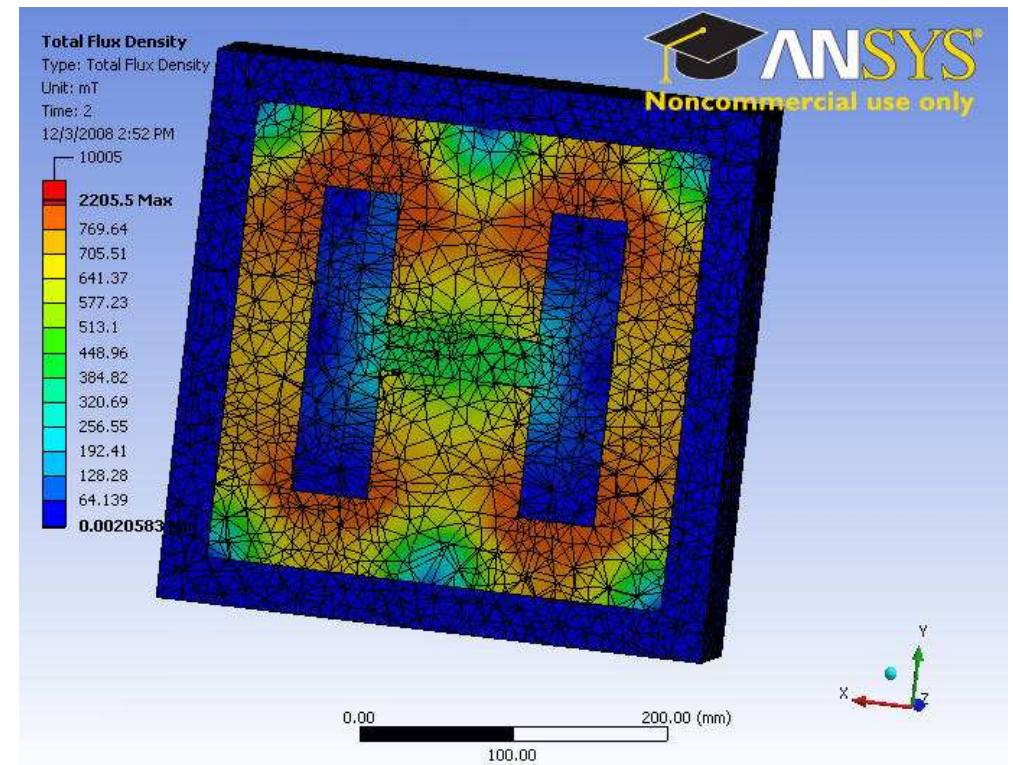
# Ongoing Magnet Design



Placeholder for final magnet design

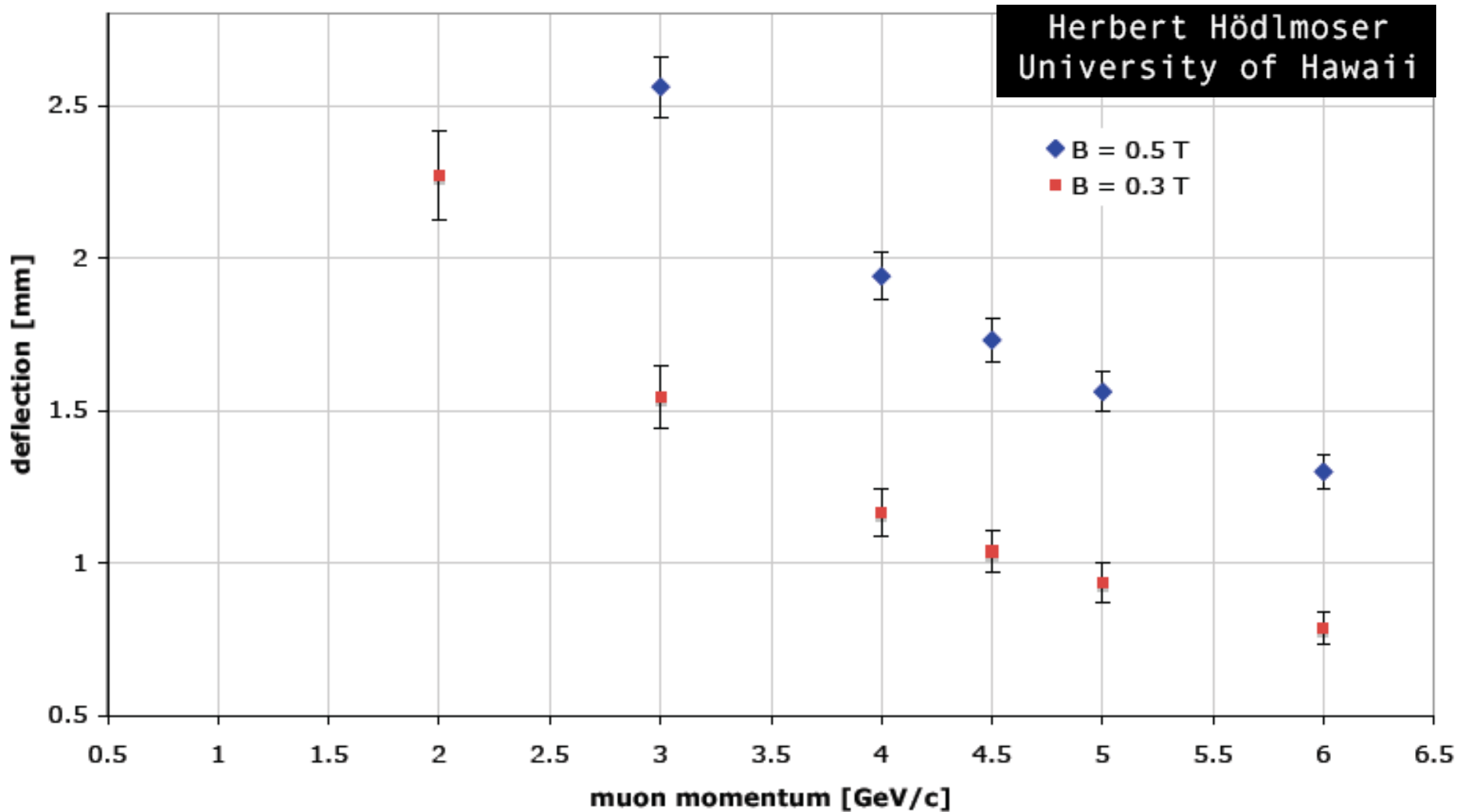
2+2 DSSD Ladders

- Readout to be integrated via fiberoptic with the rest of the assembly.



- FEA flux density simulations – Marc Rosen
- Magnet design by Bryce Jacobsen and Marc Rosen

# Simulation of Muon Deflection w/ DSSDs

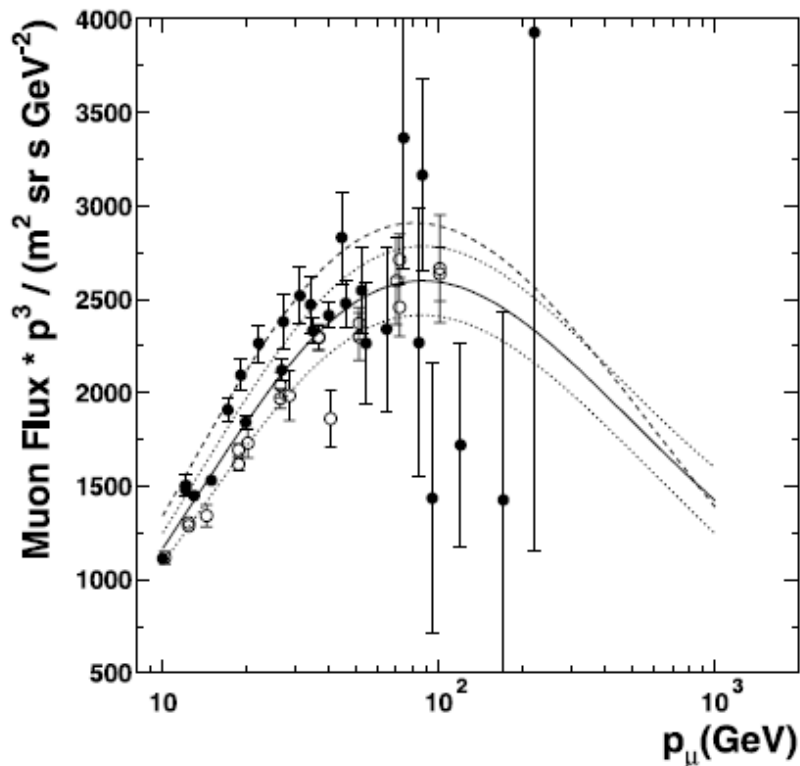


Higher field strength = improved momentum resolution

Current target: 0.5-0.6 T

# Estimates of Event Rates

	Precision Timing Trigger	> 9 “good” hits, reasonable fits	Projected to hit momentum selector
<b>Events Collected</b>	$4.94 \times 10^6$	4587	240
<b>% of Total Events</b>	100%	0.1%	0.0049%
<b>Estimated Events Per Day</b>	$1.3 \times 10^5$	121	6.3



Based on  $\sim 1.5$  months of running in original configuration.

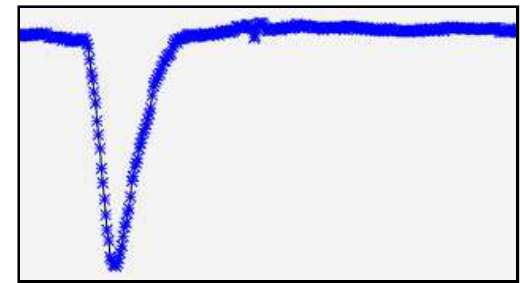
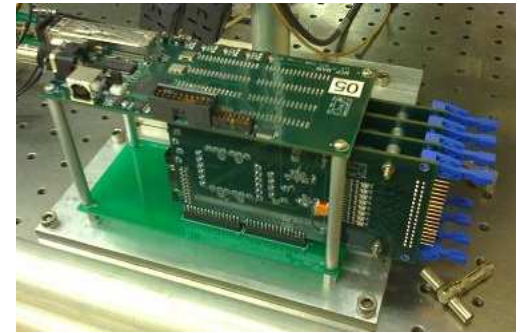
We roughly estimate a factor of  $\sim 2x$  improvement from upgrades to tracking readouts, new PT block.

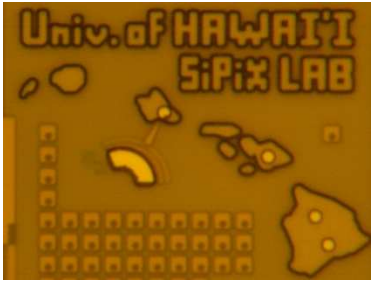
Higher energy muons may be rare due to cosmic ray spectrum.



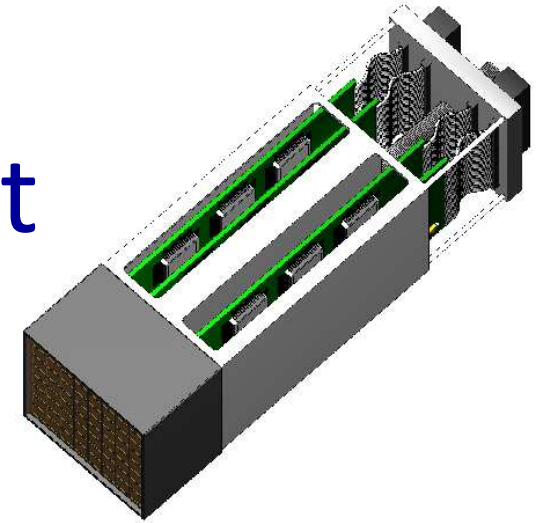
# iTOP / HI-TIDE Status

- Done:
  - Drift tubes assembled, initial performance testing with TDC readout.
- Ongoing & immediate future (~weeks):
  - All electronics now on fiberoptic readout through cPCI.
  - New waveform electronics readouts implemented, performance tests waiting on readout calibrations.
  - Readout from both sides of drift tubes.
  - Initial quartz bar readouts, comparisons with GEANT4 MC.
- Future:
  - Momentum measurements using magnet, DSSDs.
  - Improved imaging scheme.

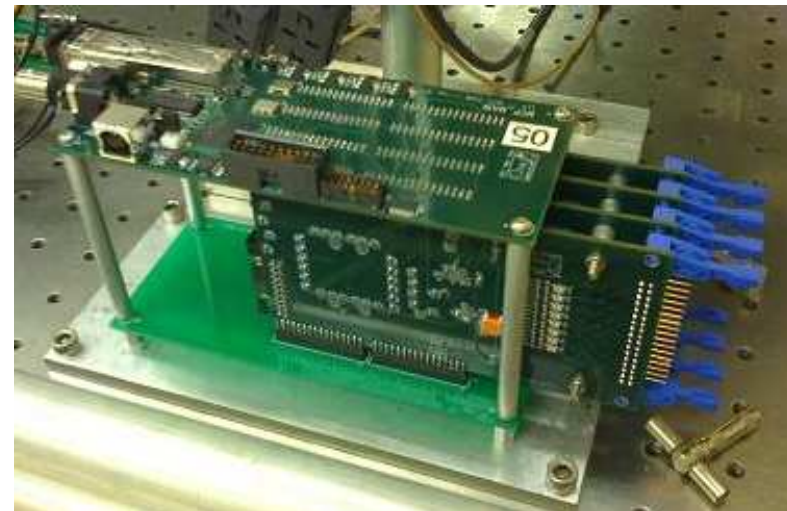
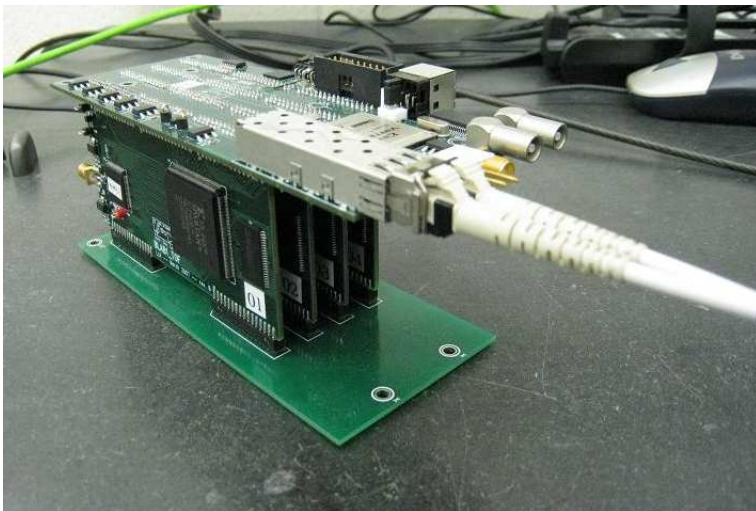




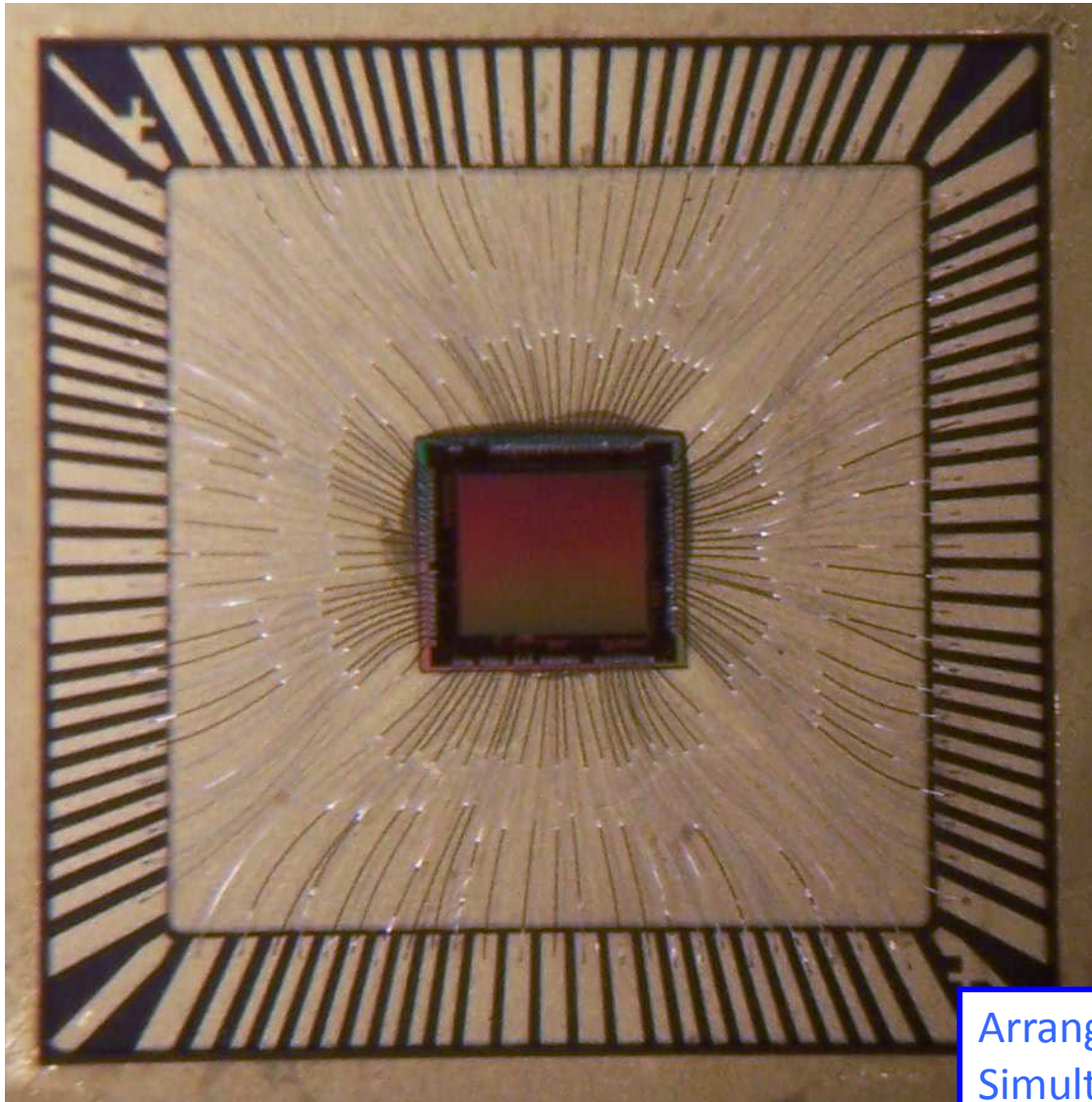
# Particle ID Readout Developments



Gary S. Varner, Larry L. Ruckman, & Kurtis Nishimura  
December 11<sup>th</sup>, 2008



# Design Basis: Buffered LABRADOR (BLAB1) ASIC



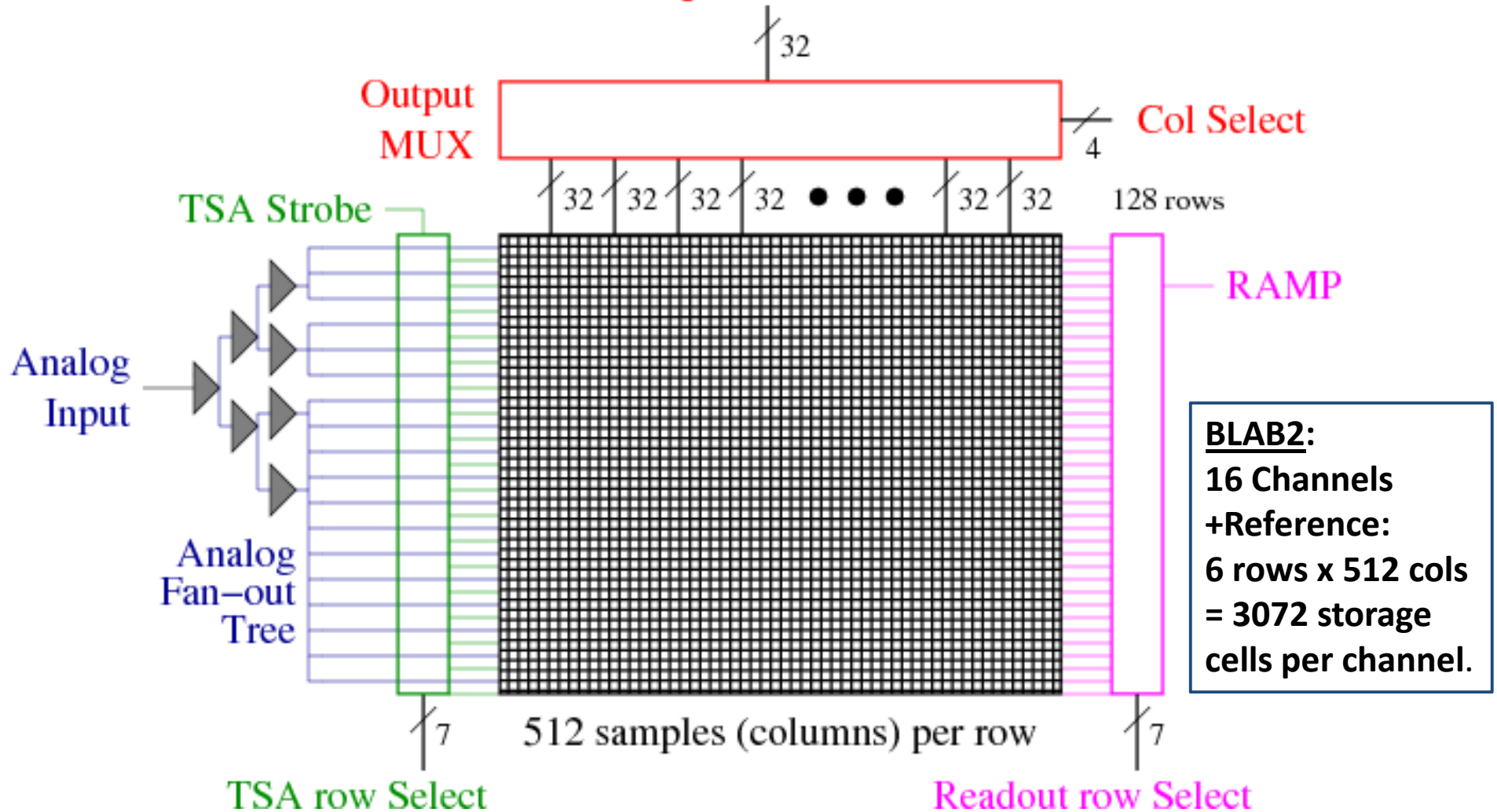
3mm x 2.8mm, TSMC 0.25um

- Single channel
- 64k samples deep, same SCA technique as LAB, no ripple pointer
- Multi-MSa/s to Multi-GSa/s
- 12-64us to form Global trigger
- BLAB1 details at:  
**NIM A591: 534-545, 2008**

Arranged as 128 x 512 samples  
Simultaneous Write/Read

# BLAB1 Architecture

Outputs to FPGA



FPGA-based TDC: 10-bits in 1us (300ps resolution)

# Highly Integrated Readout

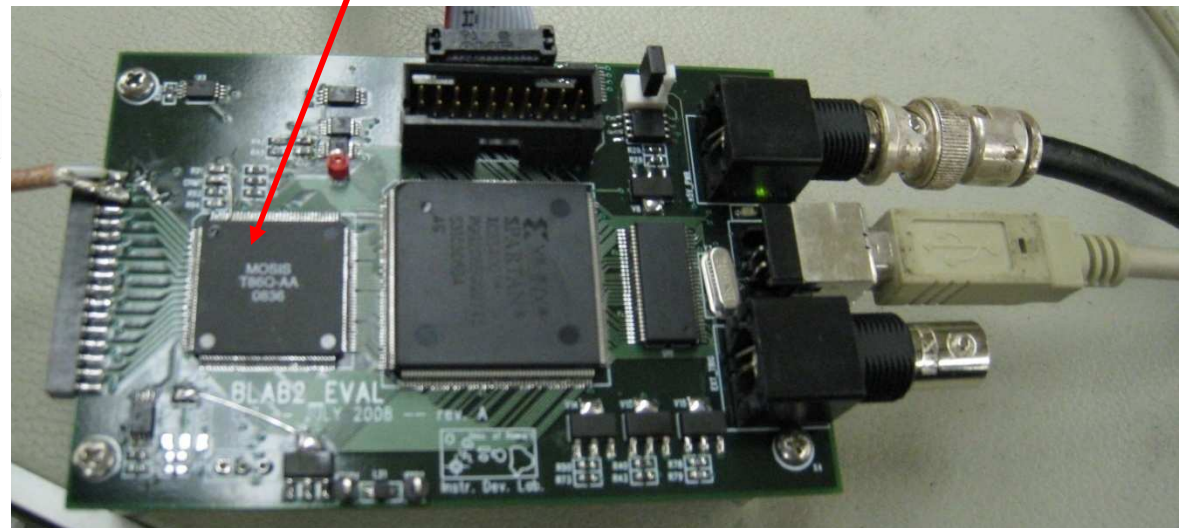
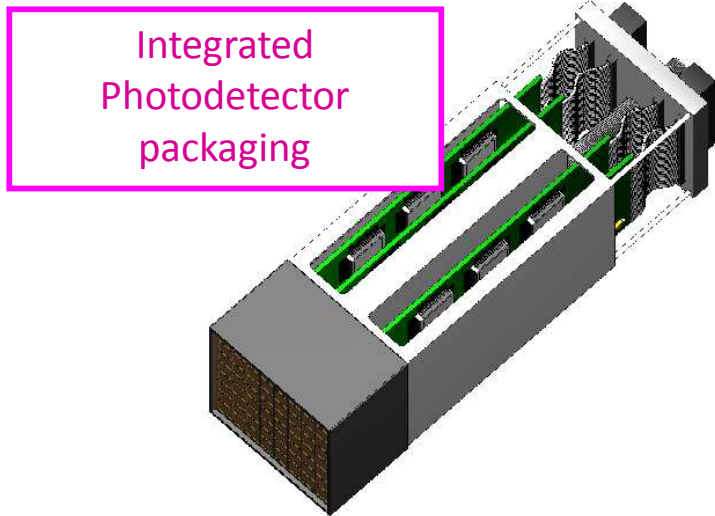
- **Buffered LABRADOR**

TABLE II: *BLAB2 ASIC Specifications.*

Item	Value
Photodetector Input Channels	16
Linear sampling arrays/channel	<del>2</del> 6
Storage cells/linear array	<del>512</del> 1024
Sampling speed (Giga-samples/s)	2.0 - 10.0
Outputs (Wilkinson)	32

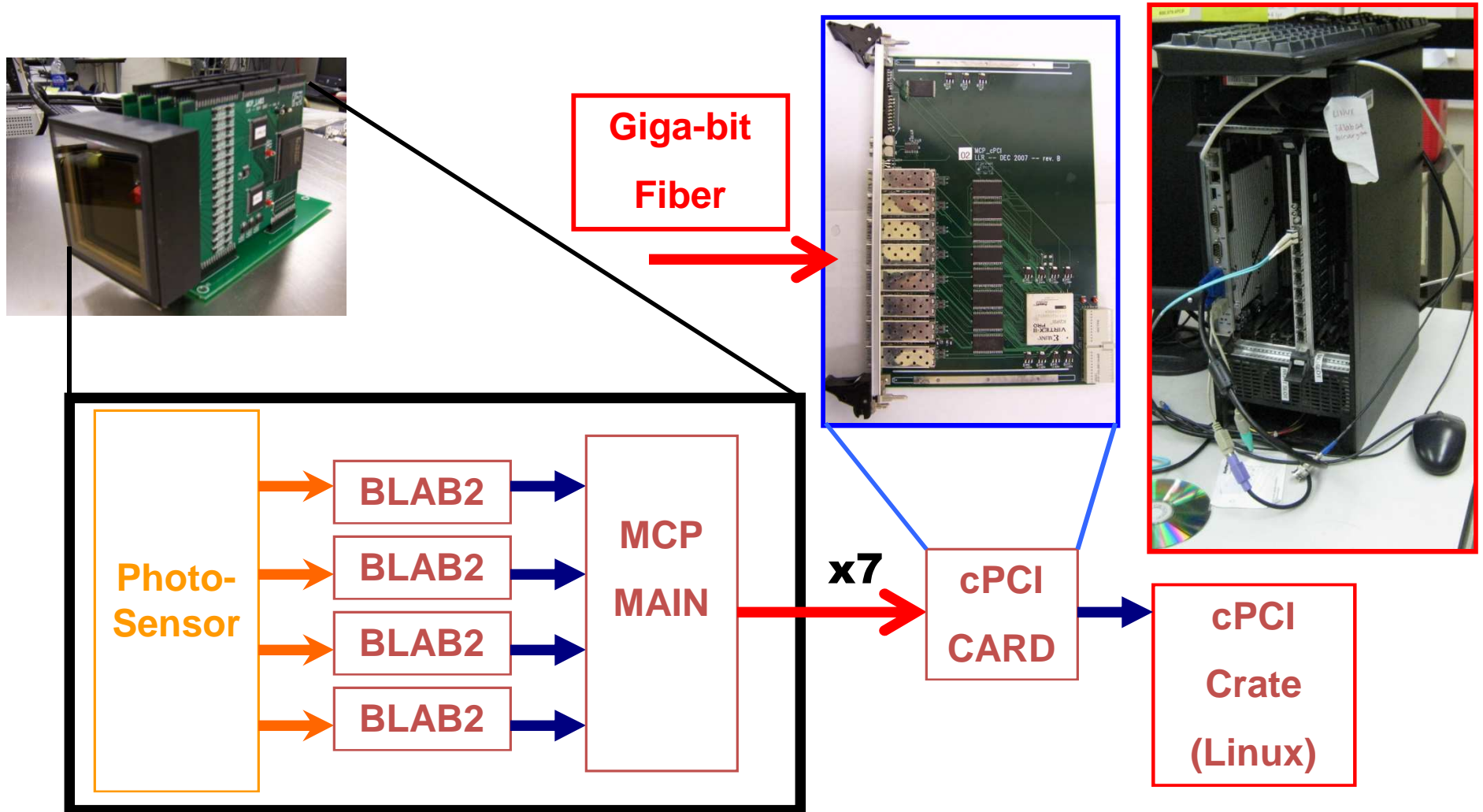


**BLAB2 ASIC**



**BLAB2 ASICs recently received: now being tested & calibrated!** 21

# Readout System Block Diagram

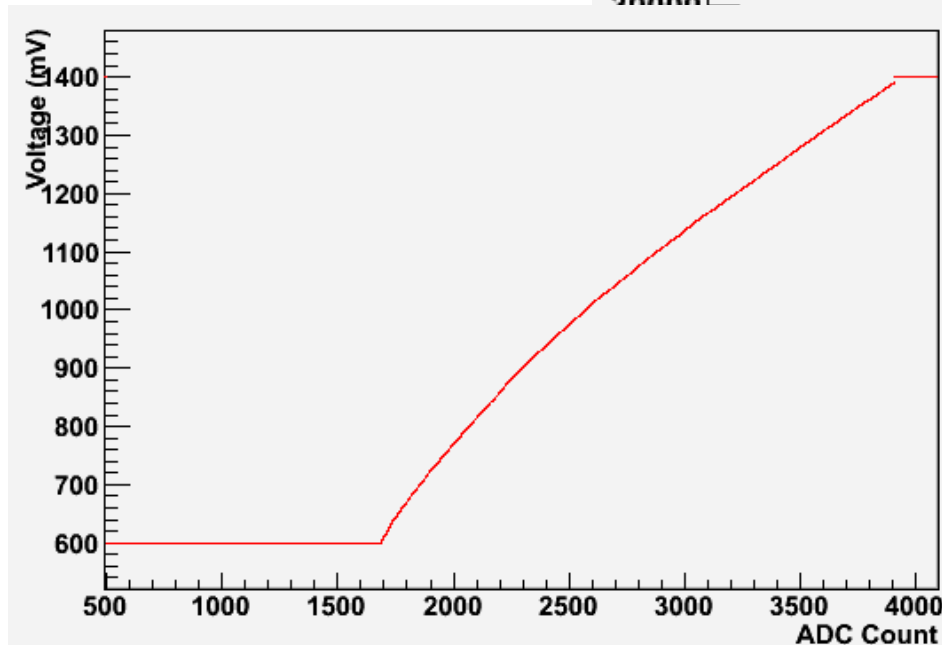
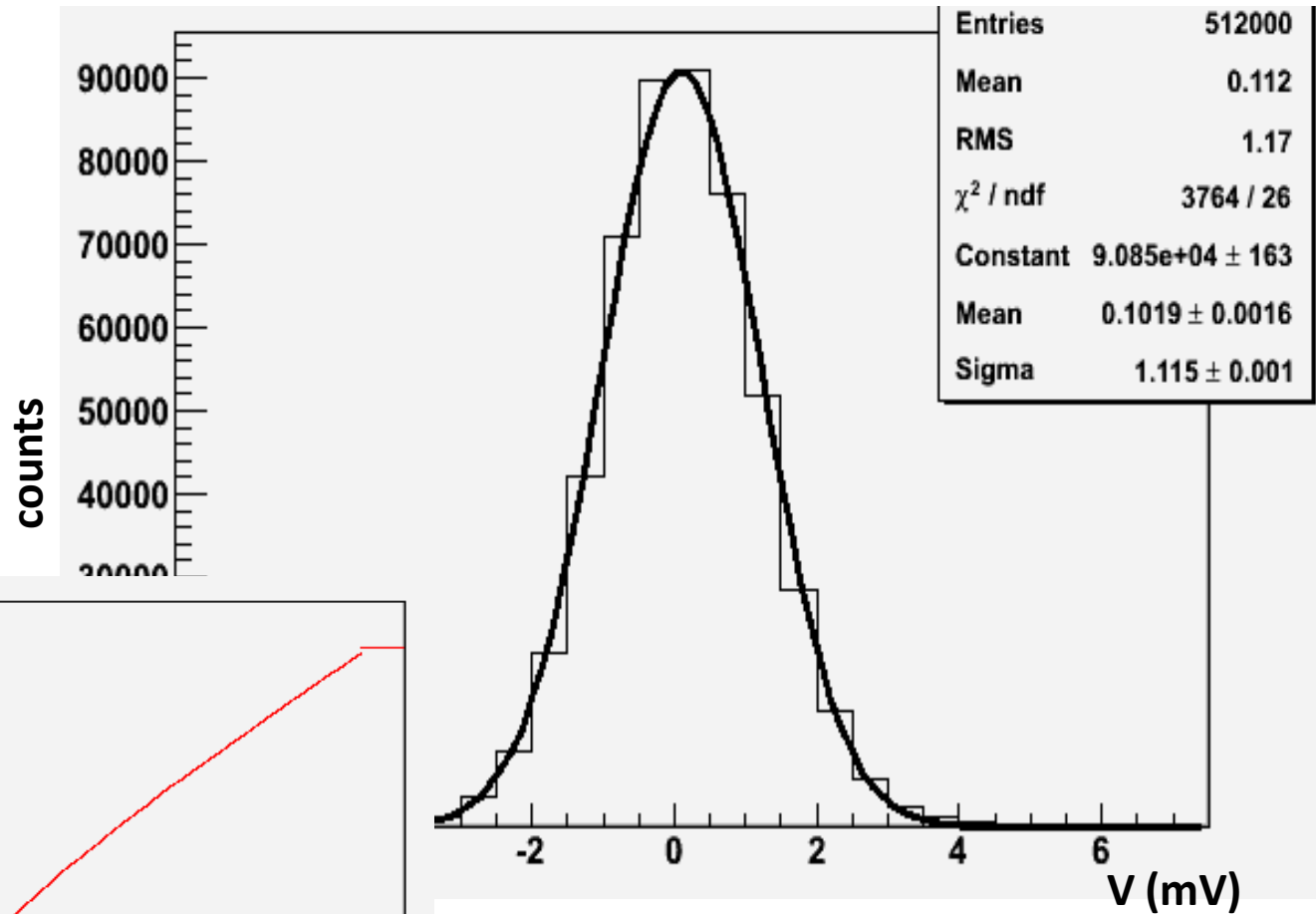


- Up to 7x64 channels per cPCI card
- Very portable DAQ
- Up to 32,256 channels/cPCI crate

**Very cost effective, board hardware already exists, firmware/software dev.**

# BLAB2 Range & Noise Performance

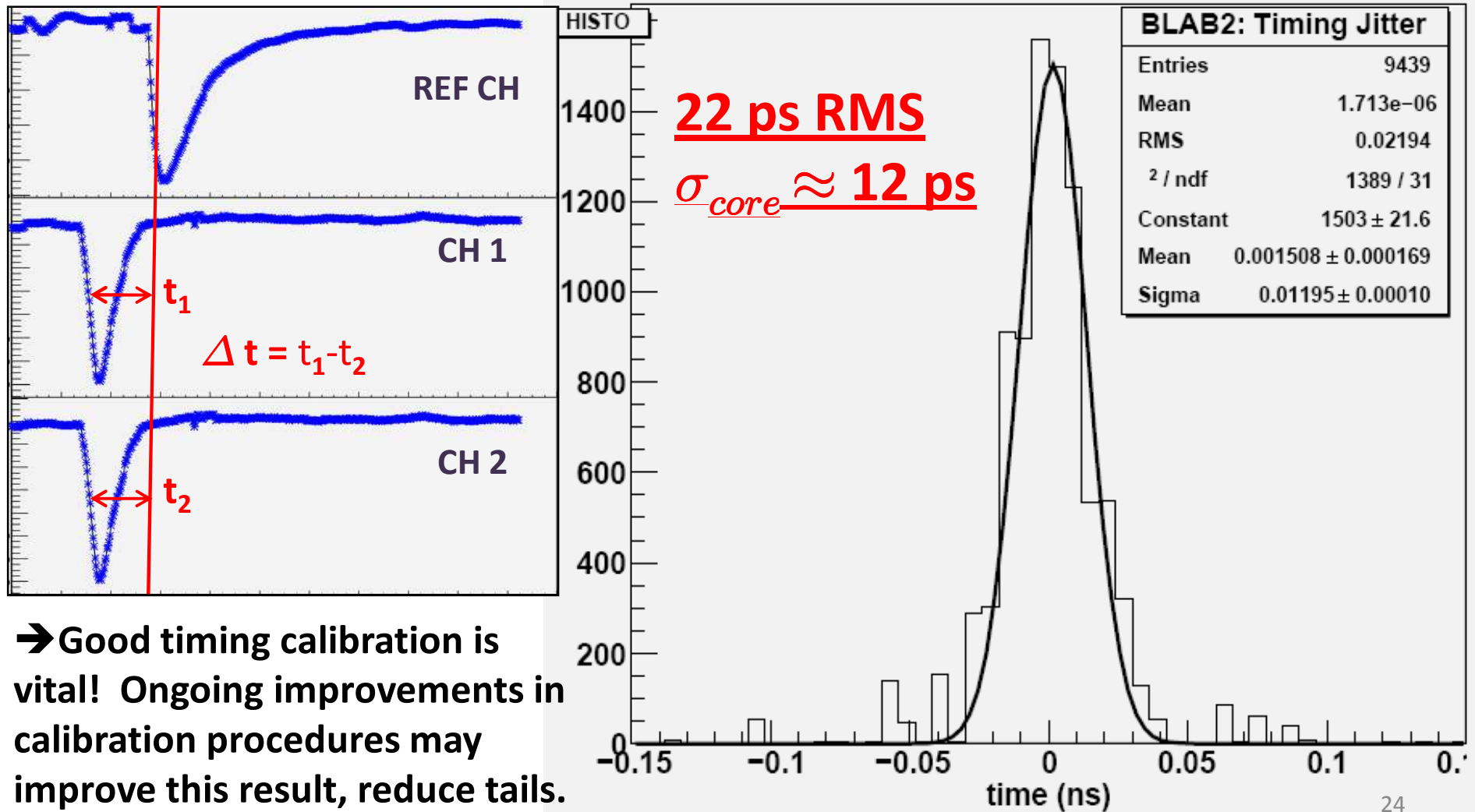
Noise levels  
after  
pedestal  
calibration:  
 $\sigma \approx 1$  mV



Dynamic range: 800 mV  
Amplifier on input for small  
amplitude (1 p.e.) detection.

# BLAB2 Timing Performance

Measured timing jitter between two channels (same BLAB2).





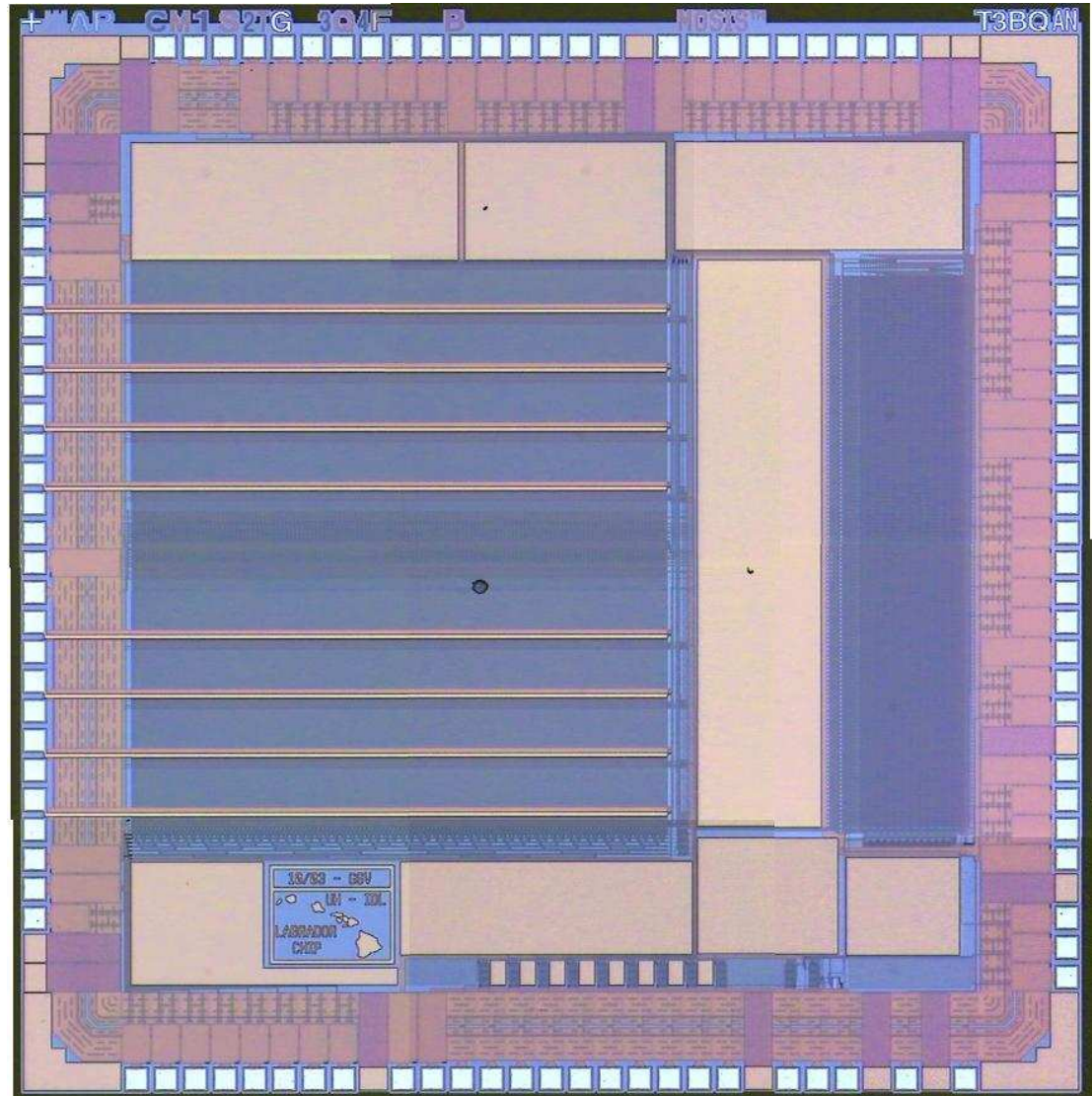
# BLAB2 Overview

- Initial noise/timing performance comparable to BLAB1:
  - Limits of calibration are being explored, may ultimately improve performance.
  - Other performance parameters will be measured soon.
- Extremely flexible readout solution:
  - Variable sampling speed, depth.
  - Being tested at HI-TIDE with drift tubes, DSSDs, PMTs, solid state photon detectors.
    - All are integrated into a unified cPCI system via fiberoptic.

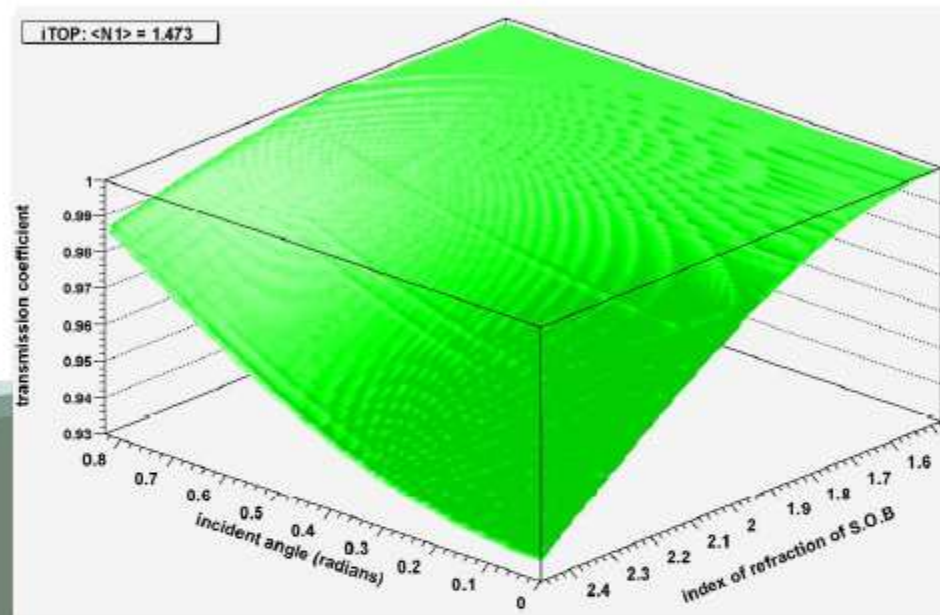
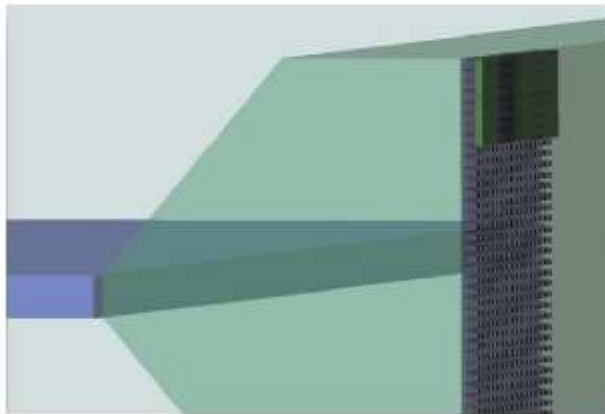
# Summary

- iTOP Status:
  - Separability performance needs experimental validation.
    - Beginning soon in Hawaii; test stand nearly complete.
  - Geometry optimization, photon detector choice
    - May be guided in part by coupling issues from SOB → detector
- PID Readout Electronics:
  - BLAB2 has been fabricated, delivered.
  - BLAB2 performance limits currently being explored.
  - To be integrated & tested very soon with photon detectors.

# Back-up slides

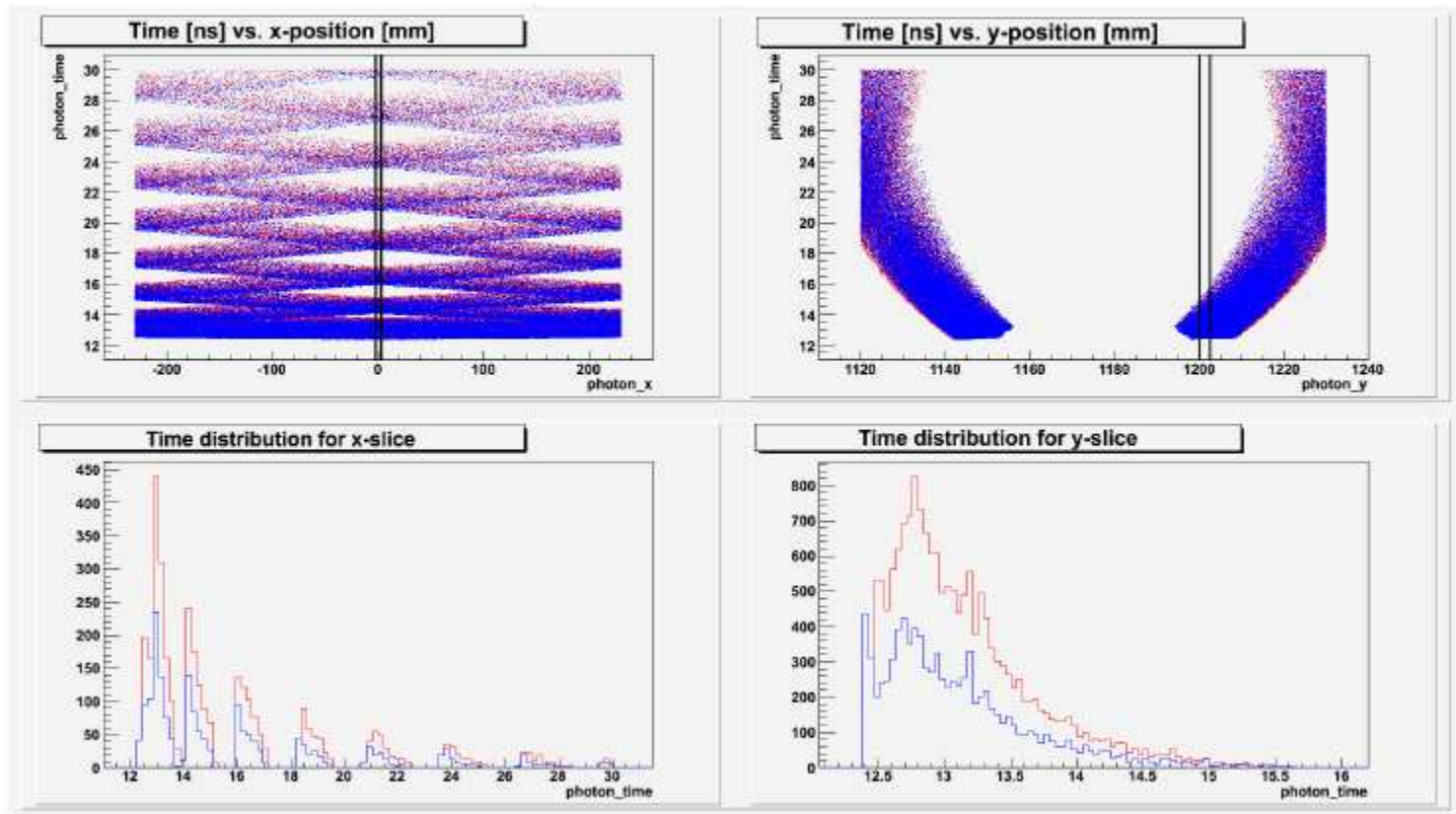


# Stand-Off Block (SOB) Coupling



44 x 92 pix/plane = 4048 channels  
16 bars x 2 ends x 4048 = ~130k channels

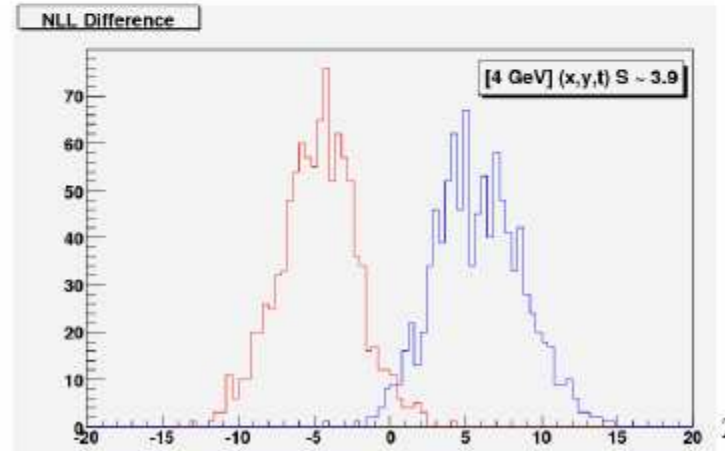
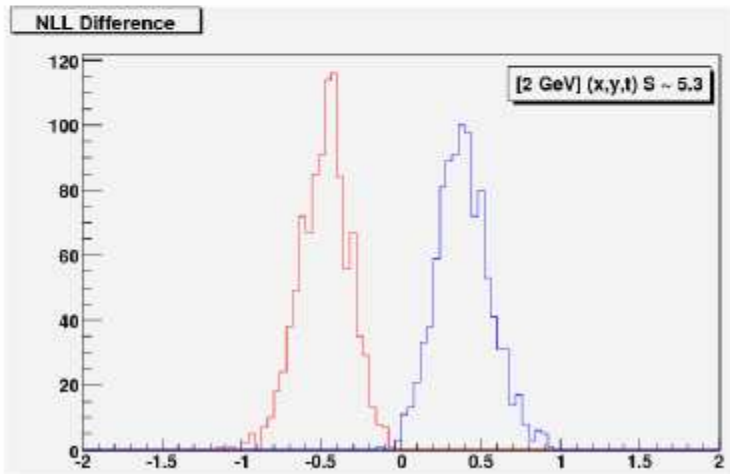
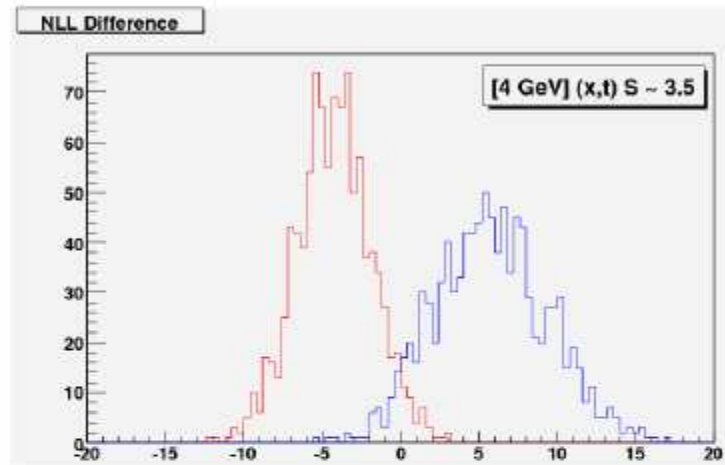
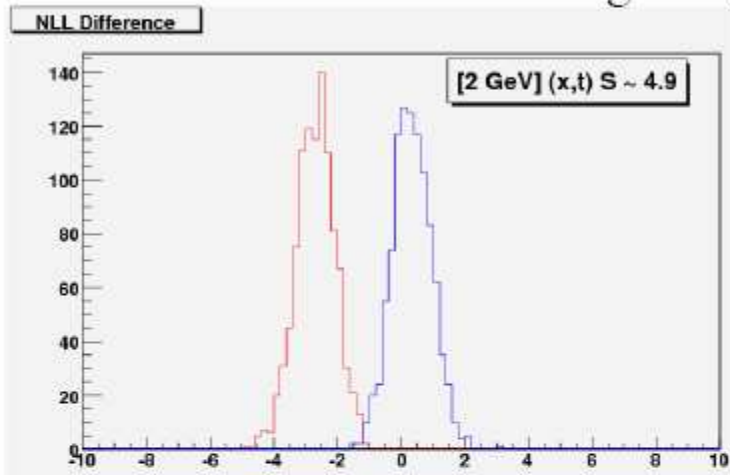
# Timing comparison



22

# Separation Concept using $\text{Log } \mathcal{L}$

90 degrees (normal incidence)



23

# simulation setup

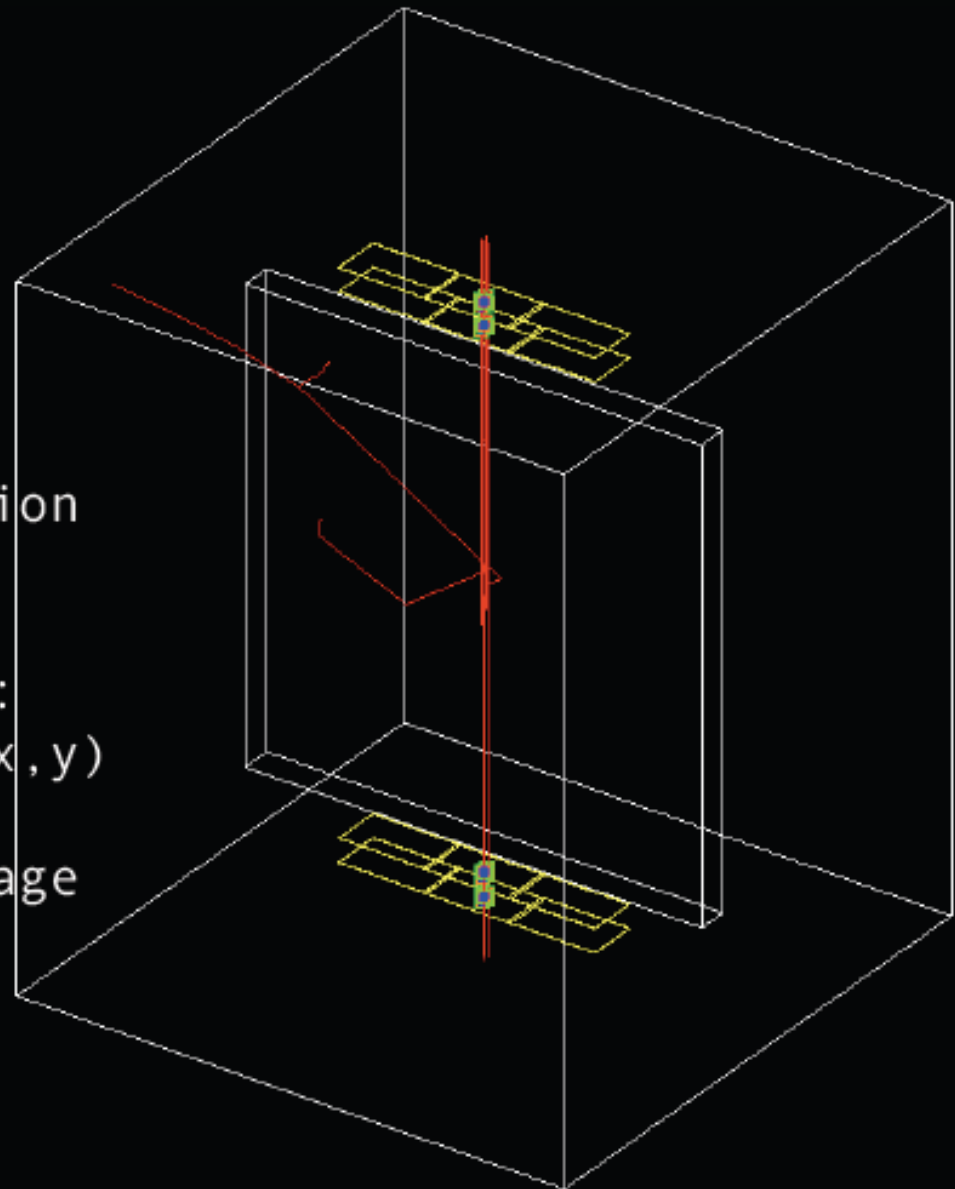
4 layers of dssd  
with gaps of 1.5 cm

primary particle:

- normal incidence
- randomized origin position  
(5 mm radius)

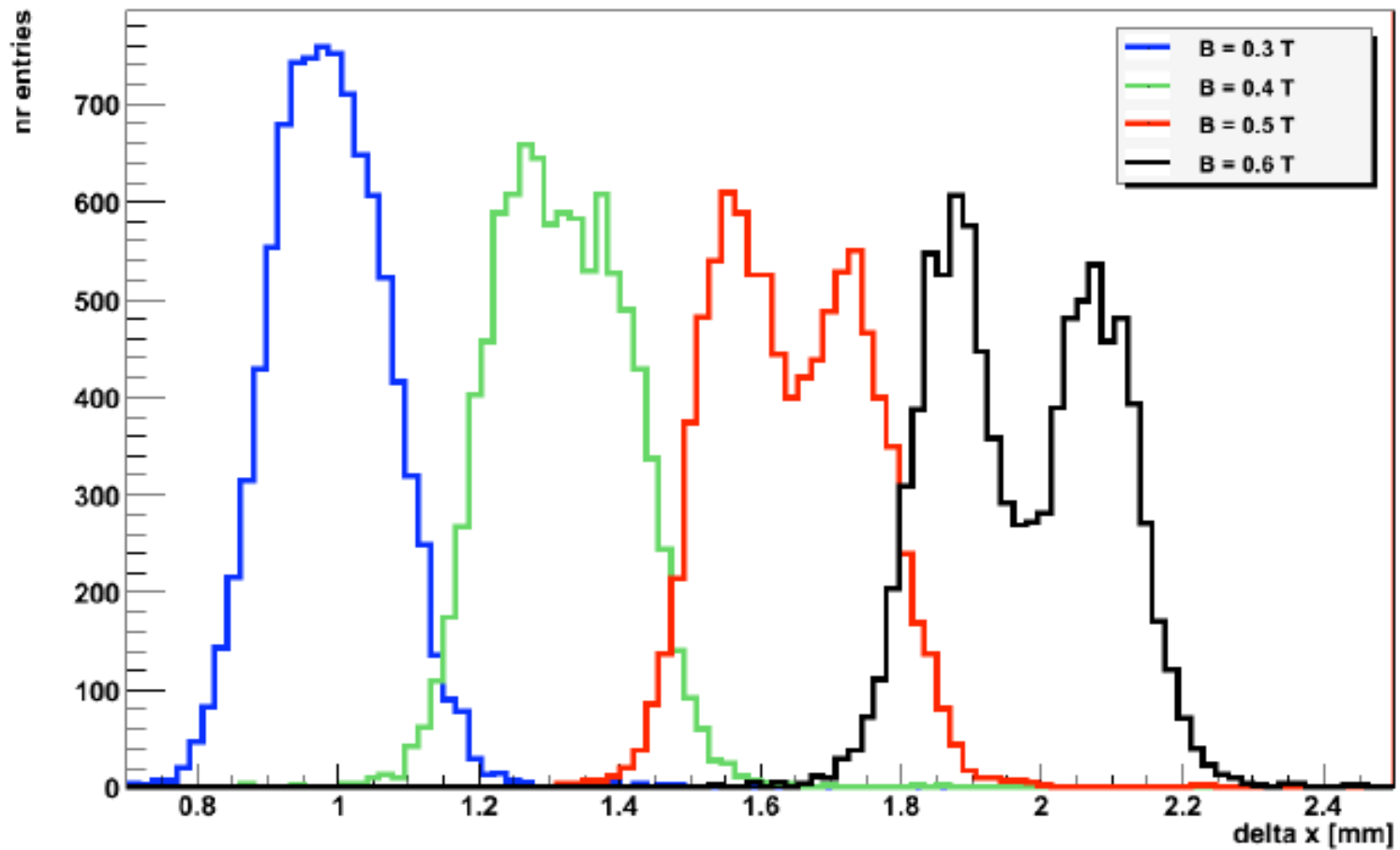
deflection calculated as:  
cluster (x,y) - origin (x,y)

in most cases as an average  
of layer 3 and 4



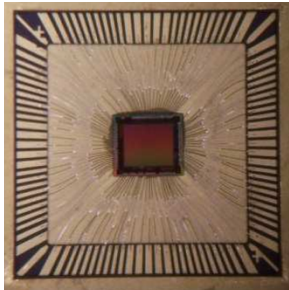
Herbert Hödlmoser  
University of Hawaii

momentum separation: 4.5 and 5 GeV/c muons

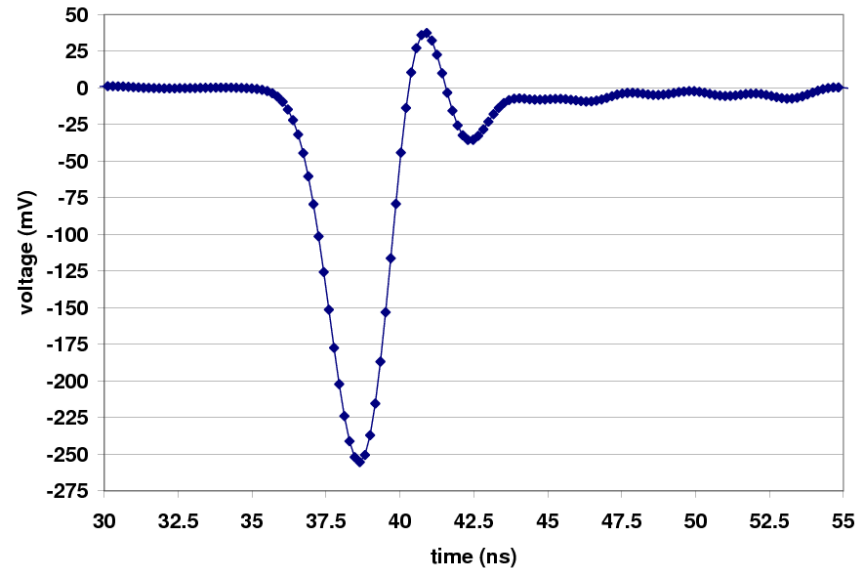
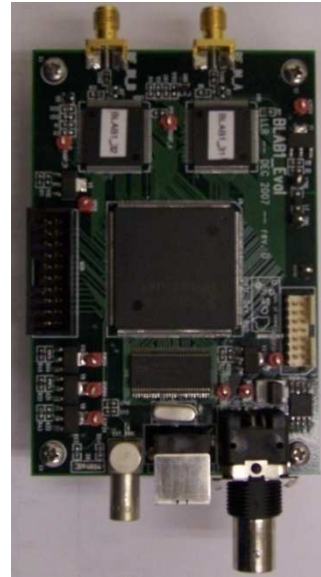




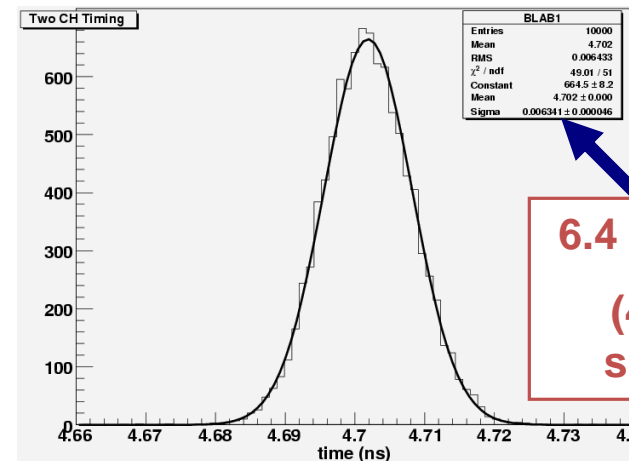
# BLAB ASIC further studies



BLAB1 -- NIM A591  
(2008) 534



- Comparable performance to best CFD + HPTDC
- MUCH lower power, no need for huge cable plant!
- Using full samples significantly reduces the impact of noise
- Photodetector limited

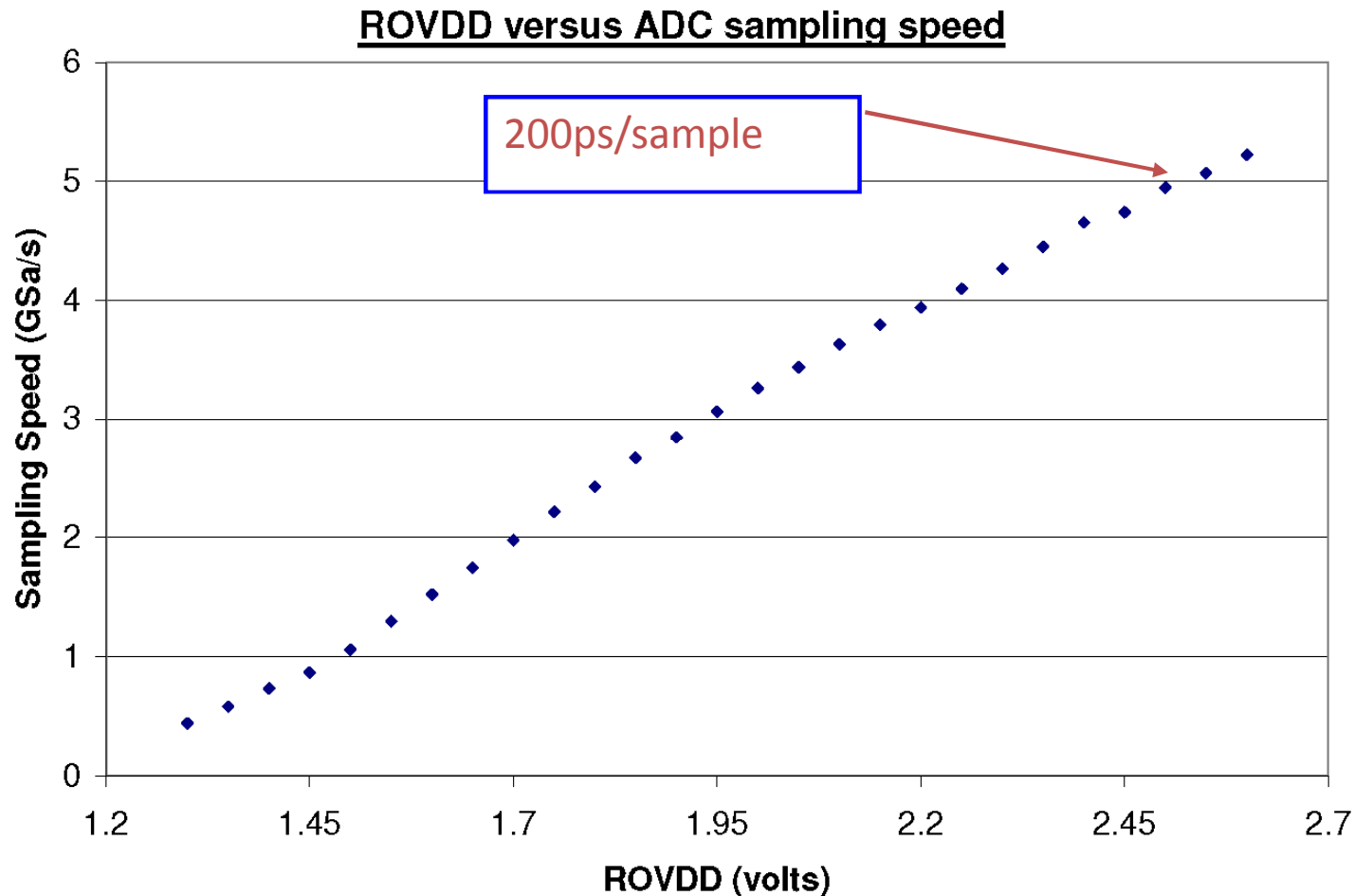


**6.4 ps RMS**  
**(4.5ps single)**

Submitted NIM, arXiv:0805.2225

# BLAB1 Sampling Speed

Can store 13us at 5GSa/s (before wrapping around)



Single sample:  
 $200/\text{SQRT}(12)$   
 $\sim 58\text{ps}$

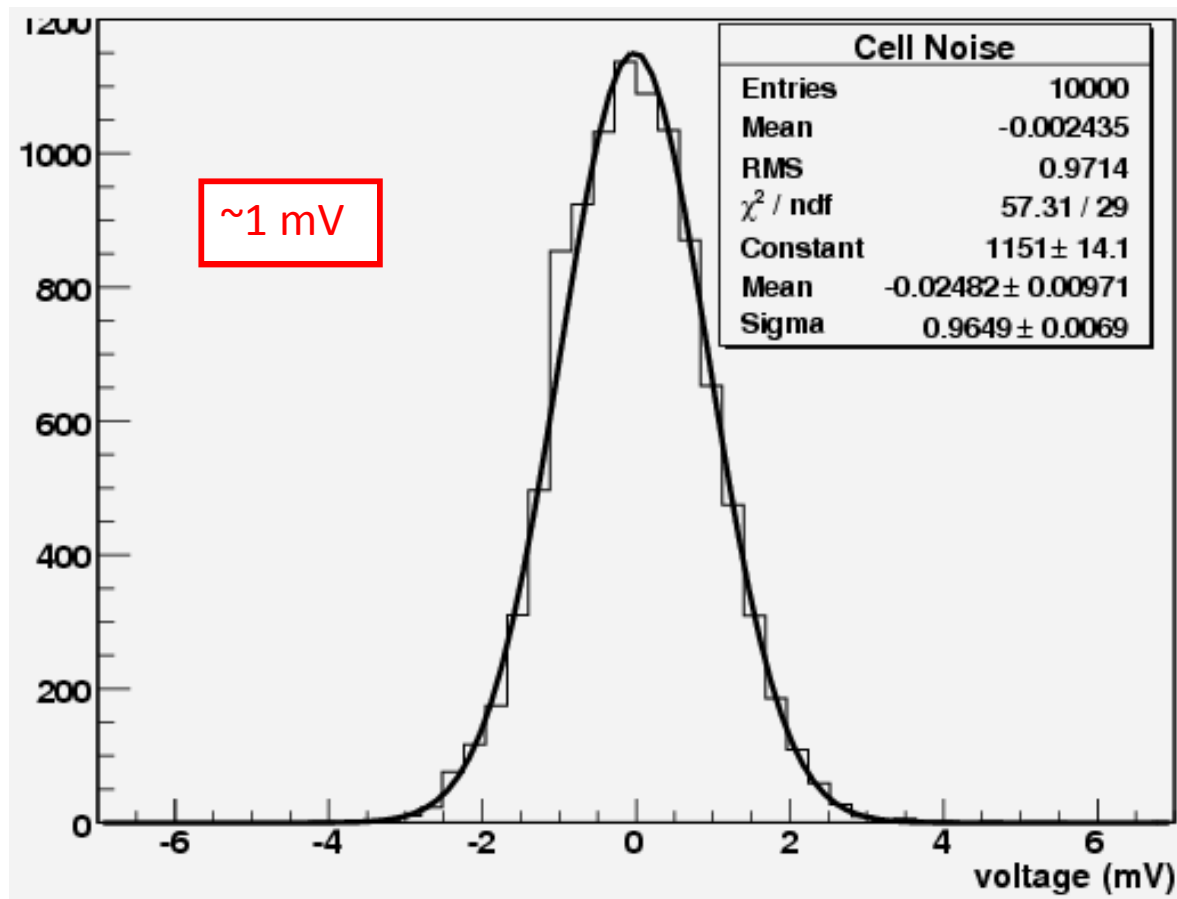
In practice, have  
often been using 512  
samples

# Buffered LABRADOR (BLAB1) ASIC

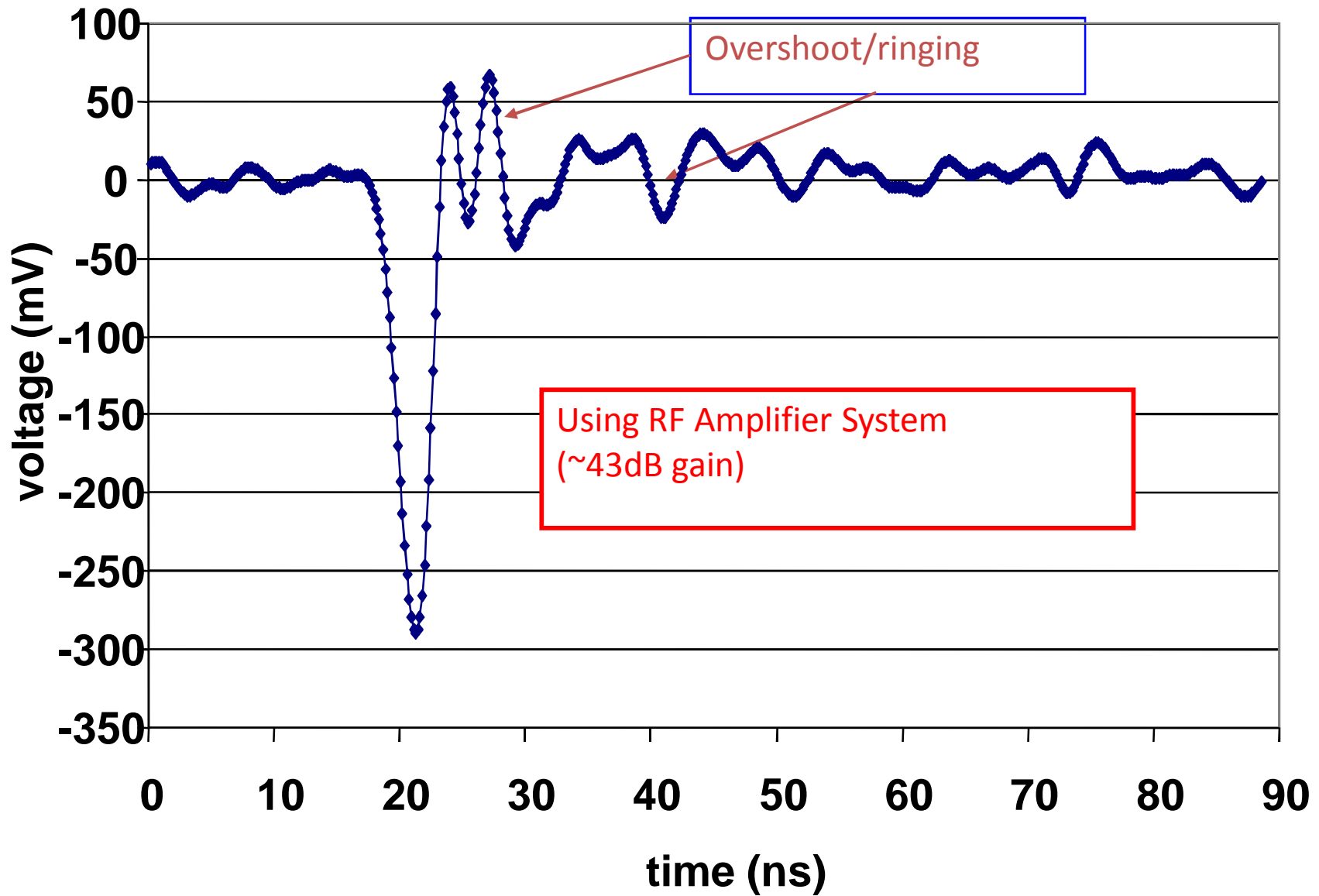
- 10 real bits of dynamic range, single-shot

## Measured Noise

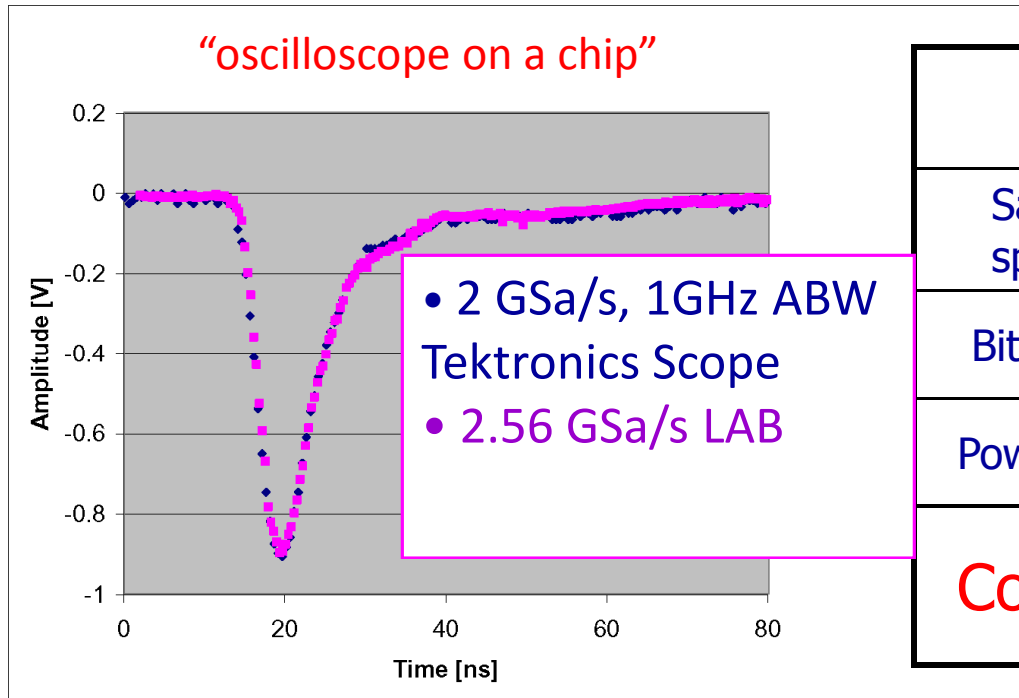
1.6V dynamic range



# Typical single p.e. signal [Burle]



# Key Enabling Technology



	LABRADOR	Commercial
Sampling speed	1-3.7 GSa/s	2 GSa/s
Bits/ENOBs	12/9-10	8/7.4
Power/Chan.	$\leq 0.05W$	5-10W
Cost/Ch.	$< \$10$ (vol)	$> 1k\$$

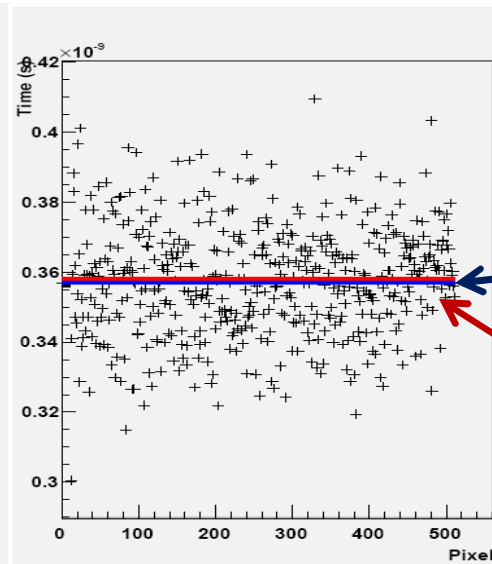
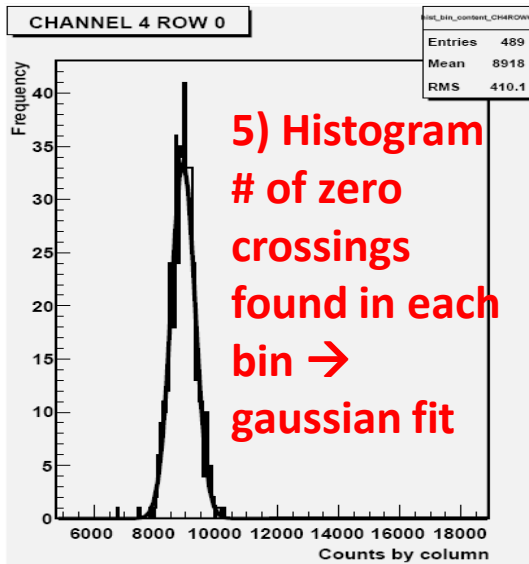
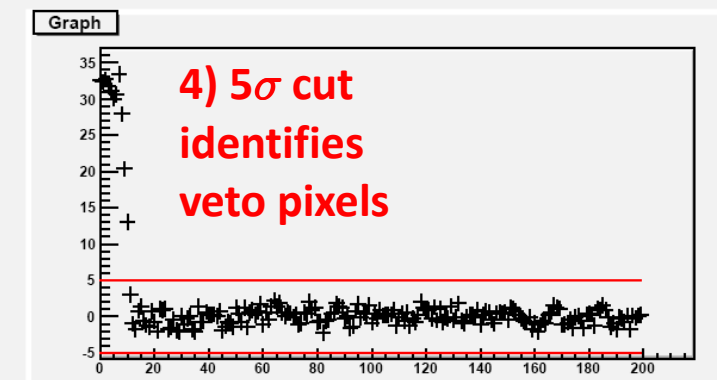
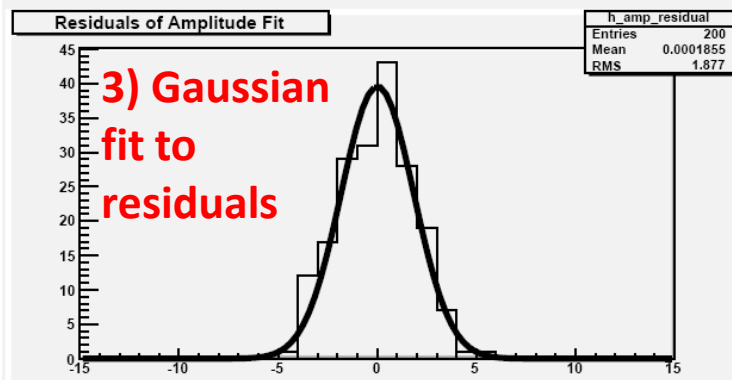
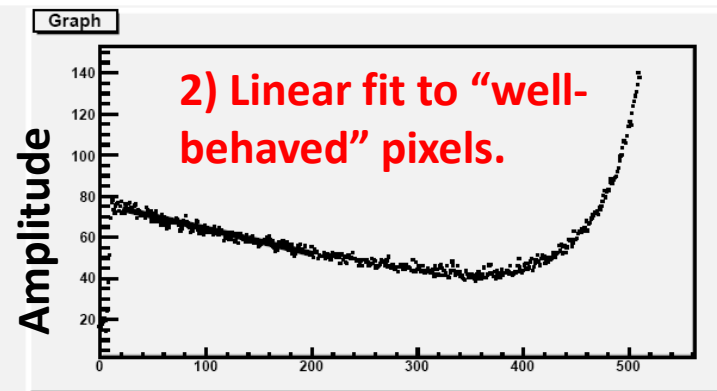
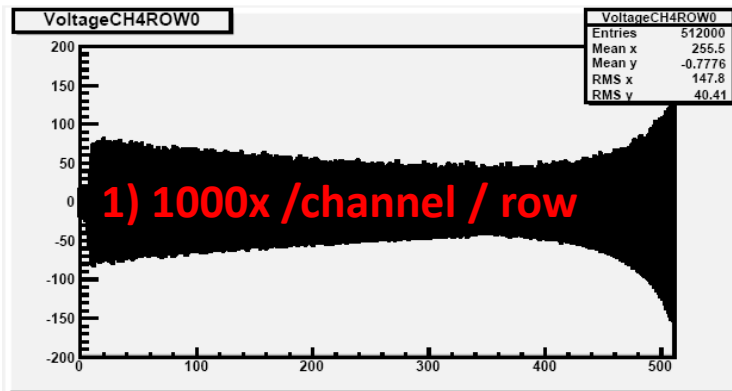
1. PoS PD07: 026, 2006
2. NIM A583: 447-460, 2007
3. NIM A591: 534-545, 2008
4. arXiv: 0805.2225 (submitted NIM A)

# BLAB2:

## Veto/Timing Calibrations

250 MHz sine wave input:

- "Veto" pixels are identified.
- Average distance between zero crossings is measured → Time per pixel is calculated.

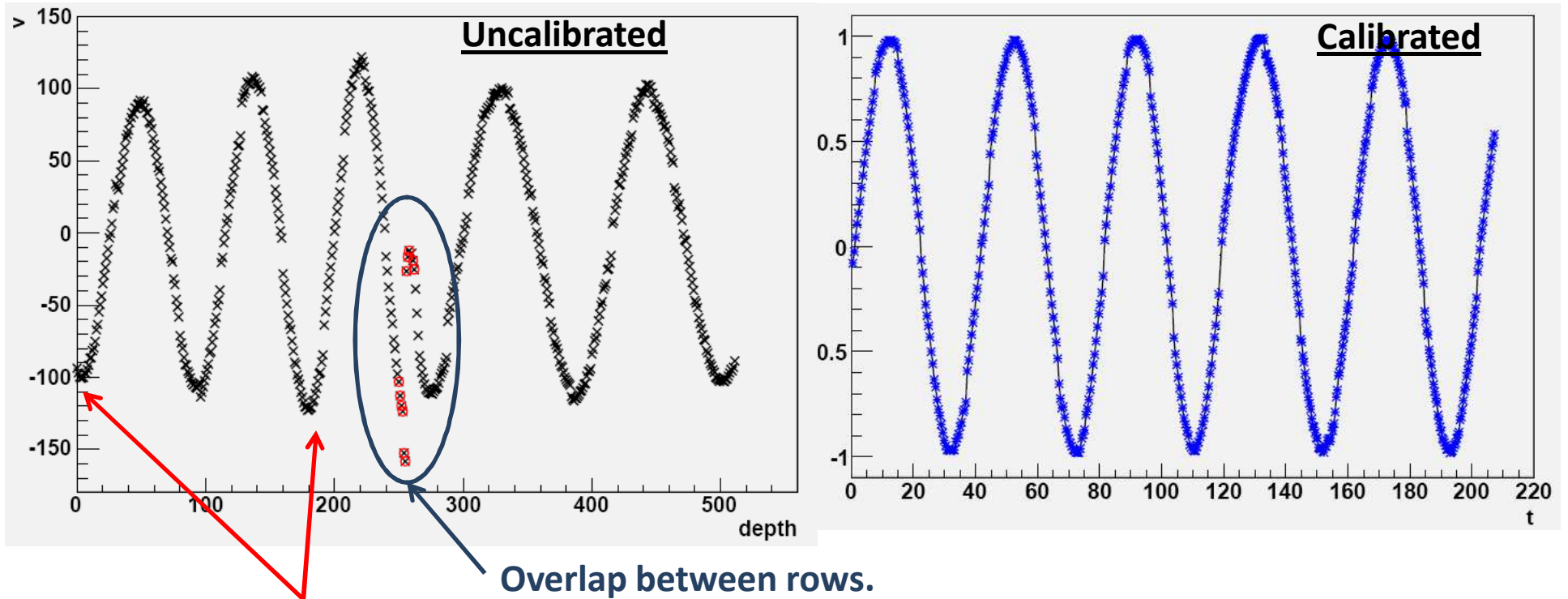


Blue line – expected mean time per pixel assuming uniform sampling

Red line – measured mean time per pixel from zero crossings

# BLAB2 Gain/Offset Calibration

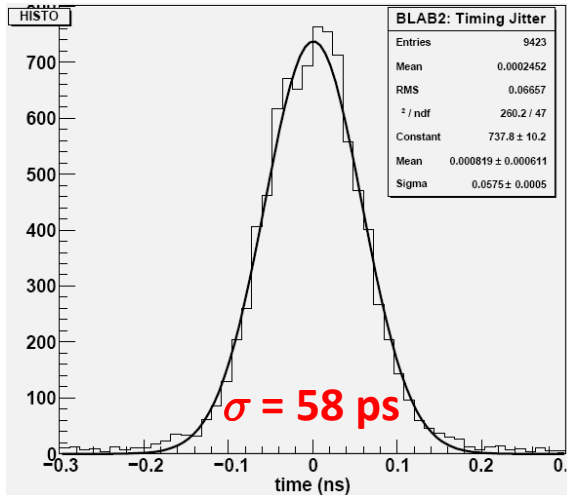
- Each pixel has unique frequency response.
- During transitions from row to row, some overlap (double sampling) occurs.
- These corrections lead to improved timing calibrations & performance.



**Gain varies with pixel position.**

# BLAB2 Timing Performance

- Measured timing jitter between two channels of a BLAB2.



Top – Before row overlap correction.

Right – After correction.

**→ Good timing calibration is vital! Ongoing developments may improve this result & remove outliers.**

